

# **Operational Semantics and Behavioural Equivalence**

**Ernesto Posse**

**August 2, 2001**

## Introduction

- Languages and formalisms for describing, modelling and simulating systems (models  $\approx$  programs).
- **Syntax:**
  - What are the entities described in the language or formalism.
  - How to combine the entities to build composite models of the systems.
- **Semantics:** The meaning of the programs or models described in the formalism. Without it we only have a bunch of meaningless symbols and/or diagrams.

## Semantics

- Motivation for studying semantics
  - Guideline for implementing formalisms.
  - Reasoning about formalisms and the systems described by them.
- Types of semantics
  - Operational: What is the computation that a program performs, or what is the state trajectory of a system.
  - Denotational: What abstract mathematical entity is represented (denoted) by a program or model (e.g. input-output function).
  - Translational: The semantics of a program or model is given by translating it to another language or formalism for which we already know the semantics.
  - Axiomatic: Preconditions and postconditions.

## Reasoning about systems

- Deduce properties satisfied by a system, e.g. termination, correctness, complexity, liveness, fairness, etc.
- Applications: verification, optimization, automatic program generation.
- Behavioural Equivalence:
  - Practical motivation: verification, optimization, automatic program generation.
  - Theoretical motivation: system equivalence is fundamental for semantics. A semantics without a notion of equivalence is incomplete.
  - Process/System Algebra
    - For black-box approach it is better treated in the context of Denotational Semantics, but for studying state-trajectories and interaction, Operational Semantics is better suited.

## Operational Semantics

- Term/Graph Rewriting Systems
  - A **TRS** is a  $(\mathcal{A}, \rightarrow)$ , where  $\mathcal{A}$  is *any* set, and  $\rightarrow \subseteq \mathcal{A} \times \mathcal{A}$  is called a *reduction* or *reaction* relation.
  - We write  $s_1 \rightarrow s_2$  instead of  $(s_1, s_2) \in \rightarrow$  to mean “ $s_1$  evolves in one time step into  $s_2$ ”, or “ $s_1$  is substituted by  $s_2$ ”
  - The operational semantics of a language are given by defining the appropriate  $\mathcal{A}$  and  $\rightarrow$ .
  - In general it is straightforward to generate an interpreter from a TRS.

## TRS example: CCS

- Communicating Concurrent Systems (Milner '79)
  - Several concurrent *processes* or *agents*, possibly composite.
  - Communication by channels: synchronous message passing.
- Syntax
  - Nil process:  $0$
  - Send a signal:  $\bar{a}.P$
  - Receive a signal:  $a.P$
  - Parallel composition:  $P_1 \mid P_2$
  - Restriction (scoping):  $\nu x.P$
- Example 1:  $\bar{a}.0 \mid a.0$
- Example 2:  $\bar{a}.b.P_1 \mid \bar{b}.a.P_2$
- Example 3:  $\bar{b}.P_1 \mid b.\nu a.(\bar{a}.P_2 \mid a.P_3)$

## TRRS example: CCS (cont.)

- Let  $\mathcal{A}_{ccs}$  be the set of all CCS programs, so the operational semantics of CCS is the TRRS  $(\mathcal{A}_{ccs}, \rightarrow)$  where  $\rightarrow$  is defined (inductively) as follows:
  - Comm:  $\bar{a}.P_1 \mid a.P_2 \rightarrow P_1 \mid P_2$
  - Par: if  $P_1 \rightarrow P'_1$  then  $P_1 \mid P_2 \rightarrow P'_1 \mid P_2$ .
  - Restr: if  $P_1 \rightarrow P'_1$  then  $\nu x.P_1 \rightarrow \nu x.P'_1$ .
- Example 1:  $\bar{a}.0 \mid a.0 \rightarrow 0 \mid 0$
- Example 2:  $\bar{a}.b.P_1 \mid \bar{b}.a.P_2 \not\rightarrow$
- Example 3:  $\bar{b}.P_1 \mid b.\nu a.(\bar{a}.P_2 \mid a.P_3) \rightarrow P_1 \mid \nu a.(\bar{a}.P_2 \mid a.P_3) \rightarrow P_1 \mid \nu a.(P_2 \mid P_3) \rightarrow \dots$

## Operational Semantics

- Labelled Transition Systems (LTS)
  - Finer grained treatment of how the system behaves
  - An **LTS** is a  $(\mathcal{A}, \mathcal{L}, \rightarrow)$ , where  $\mathcal{A}$  and  $\mathcal{L}$  are *any* sets, and  $\rightarrow \subseteq \mathcal{A} \times \mathcal{L} \times \mathcal{A}$  is called a *transition* relation.
  - We write  $s_1 \xrightarrow{\alpha} s_2$  instead of  $(s_1, \alpha, s_2) \in \rightarrow$  to mean “ $s_1$  evolves in one time step into  $s_2$  by performing the action  $\alpha$ ”.
  - Context sensitive:  $\mathcal{L}$  represents context information.
  - Closely related to automata: given an LTS  $(\mathcal{A}, \mathcal{L}, \rightarrow)$  and a system  $s \in \mathcal{A}$  we can obtain a state automata representing  $s$ .



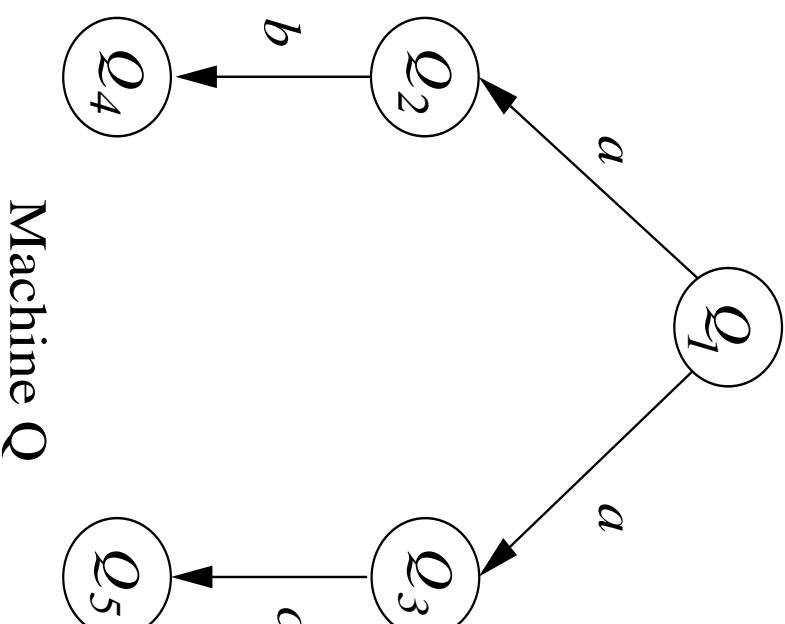
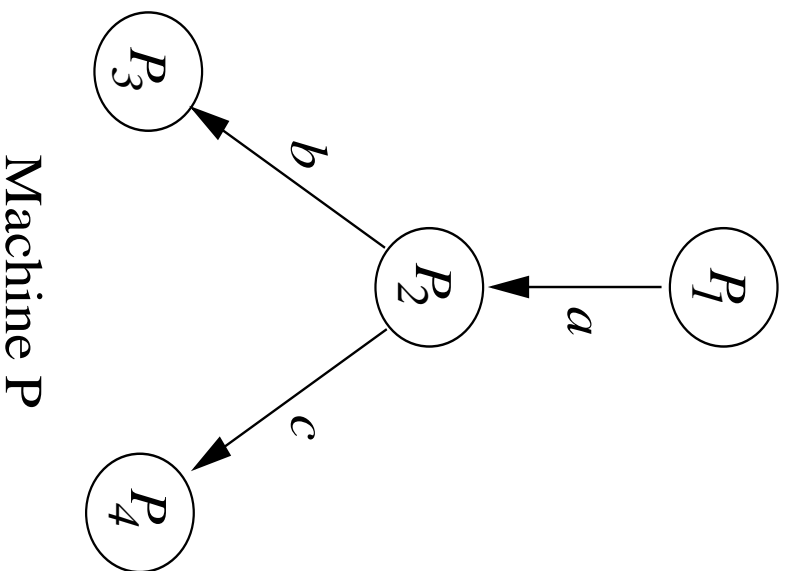
## LTS example: CCS

- Given  $\mathcal{A}_{ccs}$  as before, and  $\mathcal{L}_{ccs} \stackrel{def}{=} \{\tau\} \cup \bigcup\{x, \bar{x}\}$  for all channel names  $x$ , the semantics of CCS is given by the LTS  $(\mathcal{A}_{ccs}, \mathcal{L}_{ccs}, \rightarrow)$  where  $\rightarrow$  is defined as follows:
  - Pref:  $\alpha.P \xrightarrow{\alpha} P$
  - Comm: if  $P \xrightarrow{\bar{a}} P'$  and  $Q \xrightarrow{a} Q'$  then  $P \mid Q \xrightarrow{\tau} P' \mid Q'$
  - Par: if  $P_1 \xrightarrow{\alpha} P'_1$  then  $P_1 \mid P_2 \xrightarrow{\alpha} P'_1 \mid P_2$ .
  - Restr: if  $P_1 \xrightarrow{\alpha} P'_1$  and  $x$  is not in  $\alpha$  then  $\nu x.P_1 \xrightarrow{\alpha} \nu x.P'_1$ .

## Simulation and similarity

- Formalize the notion of “one system/model imitates another system/model”.
  - Do no separate the world from the formalism domain.
  - The “simulating” system must match the actions of the “simulated” system.
- Given an LTS  $(\mathcal{A}, \mathcal{L}, \rightarrow)$ , a binary relation  $S \subseteq \mathcal{A} \times \mathcal{A}$  is called a *simulation* if for any  $P, Q \in \mathcal{A}$ ,  $(P, Q) \in S$  implies that whenever  $P \xrightarrow{\alpha} P'$  for some  $\alpha \in \mathcal{L}$  and some  $P' \in \mathcal{A}$  then  $Q \xrightarrow{\alpha} Q'$  for some  $Q' \in \mathcal{A}$  and  $(P', Q') \in S$ .
- We say that  $P$  and  $Q$  are *similar* (or that  $Q$  *simulates*  $P$ ), written  $P \preceq Q$  if there is a simulation  $S$  such that  $(P, Q) \in S$ .

## Simulation example



$Q_1 \preceq P_1$  because

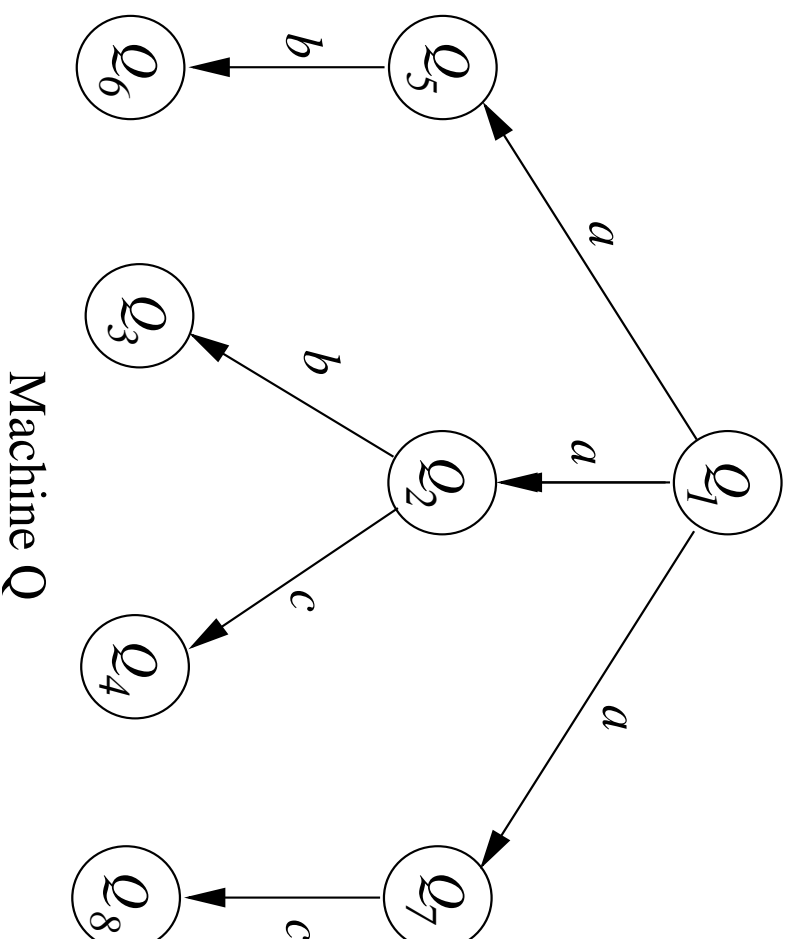
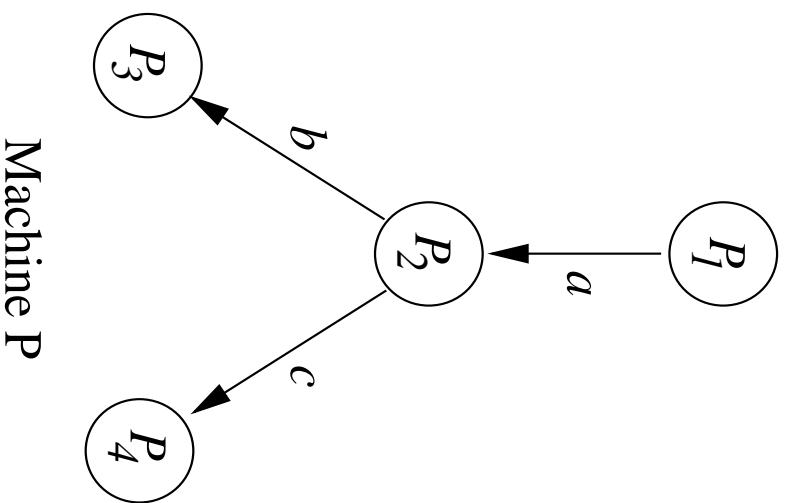
$S \stackrel{\text{def}}{=} \{(Q_1, P_1), (Q_2, P_2), (Q_3, P_2), (Q_4, P_3), (Q_5, P_4)\}$  is a simulation.

...but  $P_1 \not\preceq Q_1$

## Behavioural equivalence: first attempt

- Two-way simulation: we consider  $P$  and  $Q$  equivalent if  $P \preceq Q$  and  $Q \preceq P$ .
- Is this an equivalence relation? Yes.
- Is it a good behavioural equivalence relation? No. A good behavioural equivalence should differentiate between systems that do not have the same state trajectories.

Are these equivalent?



## Behavioural equivalence: second attempt

- Two-way simulation fails in capturing the idea that two equivalent systems must interact in the same manner with the external world (i.e. it is not a congruence)
- Given an LTS  $(\mathcal{A}, \mathcal{L}, \rightarrow)$ , a binary relation  $\mathcal{S} \subseteq \mathcal{A} \times \mathcal{A}$  is called a *bisimulation* if for any  $P, Q \in \mathcal{A}$ ,  $(P, Q) \in \mathcal{S}$  implies that for any  $\alpha \in \mathcal{L}$ :
  - Whenever  $P \xrightarrow{\alpha} P'$  then  $Q \xrightarrow{\alpha} Q'$  and  $(P', Q') \in \mathcal{S}$ .
  - Whenever  $Q \xrightarrow{\alpha} Q'$  then  $P \xrightarrow{\alpha} P'$  and  $(P', Q') \in \mathcal{S}$ .
- Alternative definition:  $\mathcal{S}$  is a bisimulation if it is a simulation and  $\mathcal{S}^{-1}$  is also a simulation.
- We say that  $P$  and  $Q$  are *bisimilar*, written  $P \sim Q$  if there is a bisimulation  $\mathcal{S}$  such that  $(P, Q) \in \mathcal{S}$ .

## Congruence relations

- When an equivalence relation is not good enough.
- Given an algebra (or language) with some operators (or combinators), we can define the notion of “context” as a term with a “hole”: if  $\mathcal{C}[\cdot]$  is a context in our formalism and  $P$  a system in the formalism (element in the algebra), then  $\mathcal{C}[P]$  is the system resulting from putting  $P$  in place of the hole  $[\cdot]$ .
- A congruence relation is an equivalence relation  $\cong$  such that whenever  $P \cong Q$ , then  $P$  and  $Q$  are interchangeable in all possible contexts, i.e. it is preserved by all contexts: for all contexts  $\mathcal{C}[\cdot]$ ,  $P \cong Q$  implies  $\mathcal{C}[P] \cong \mathcal{C}[Q]$ .
- In CCS, bisimilarity is a congruence.

## Final remarks

- A notion of behavioural equivalence should be a congruence
- ...but the notions of simulation and behavioural equivalence can (and sometimes must) be relaxed to be more useful.
  - Weak (bi)simulation
  - Barbed (bi)simulation
  - etc.
- The notion of (bi)simulation depends on the formalism, and sometimes it is not a congruence (yet might be useful). There are specialized notions, e.g. markovian bisimulation.
- The notion of bisimulation induces an algebra (set of axioms for equations).
- Bisimulation is decidable, and there are standard algorithms for testing it (but they are also formalism dependant).