Layout in Visual Modelling

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Inspired by D. Dubé, Graph Layout for domain-specific modeling (2006)

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Layered drawing technique

- Phase 1: layer assignment
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- Phase 2: crossing reduction

Greedy cycle removal

Algorithm 1 Greedy cycle removal

Input: A graph G=(V,E)

Output: An acyclic and topologically sorted graph G

- 1: $V \leftarrow topological \text{ sort of } V$
- 2: for all $v \mbox{ in } V$ do
- 3: for all child in v.getChildren() do
- 4: if $\Pi(child) < \Pi(v)$ then
- 5: reverse edge between v and child
- 6: end if
- 7: end for
- 8: end for

BFS layering

1. Find the root vertices

2. Recursively label discovered vertices the next layer

- Optimal height
- Unbounded width

Longest-path layering

1. Layering leaf vertices at layer 1

2. Vertices are added to successive layers if all their children are in layers below them

- Optimal height
- Unbounded width

Minimum width layering

- 1. Longest path algorithm
- 2. Connect all unconnected vertices Place them in the first or last layer
 - Yields drawings with good aspect ratios
 - Creates longer edges that traverse multiple layers

Crossing minimization

- Layer-by-layer sweep
 - Stores current best ordering of vertices, as compared to the best number of crossings seen so far.
 - Stopping condition:
 - Hard limit on iterations
 - Crossing reduction doesn't change
 - No crossings remain



Spring-embedder algorithm

- Edges = springs
- Vertices = rings
- Pre-processing step recommended
 → improve convergence speed and quality

Spring-embedder algorithm

- 1. Acquire center coordinates of vertices
- 2. Set 2D force vectors to zero
- 3. Set repulsion charges to diagonal lenght of vertex
- 4. Loop: calculate forces acting on vertices

Repulsion algorithm

- 1. Calculate Manhattan and Euclidean distances
- 2. Calculate scalar force
- 3. Multiply force by 2D Manhattan distance vector

- avoid vertex overlaps
- generate large repulsive forces if overlap

Attraction algorithm

• Treats edges as physical springs

- 1. Calculate Manhattan and Euclidean distances
- 2. Calculate spring force
- 3. Multiply force by 2D Manhattan distance vector

Gravity algorithm

- 1. Impart on each vector a velocity towards the gravitational field source
- 2. Calculate force vector

• Increase area usage efficiently



Force-tranfer layout algorithm

- Initialization phase
 - Set forces acting on each vertex to zero
 - Set position of vertex to its center coordinate
- Simulation phase
 - Each vertex exerts forces on overlapping neighboring vertices
 - 1. Calculate Manhattan and Euclidean distances
 - 2. Compute scalar force magnitude
- Termination
 - No more overlap
 - Fixed number of iterations



Tree-like layout algorithm

1. Find root vertices of graph

2. Recursively assign coordinates to children of root before root itself.

• Graph structures that are really trees

Circle layout algorithm

- 1. Sort vertices topologically
- 2. Calculate perimeter of circle
- 3. Calculate interval fraction

- Subgraphs or small graphs
- Preprocessing step for force directed method



Implementation project

- Effectiveness of linear constraints in AtoMPM
 - Integration of linear constraints with AtoMPM
 - Dealing with visual icons
- Layered technique in appropriate language