#### **Design-Space Exploration** 1 in Model Driven Engineering 2 -An Initial Pattern Catalogue-3 Ken Vanherpen<sup>1</sup>, Joachim Denil<sup>1,2</sup>, л Paul De Meulenaere<sup>1</sup>, and Hans Vangheluwe<sup>2,3</sup> 5 <sup>1</sup> CoSys-Lab, FTI, University of Antwerp, Belgium 6 2 AnSyMo, FWET, University of Antwerp, Belgium 7 <sup>3</sup> MSDL, McGill University, Canada 8 {ken.vanherpen, joachim.denil, paul.demeulenaere}@uantwerpen.be 9 hv@cs.mcgill.ca 10

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Abstract. A designer often has to evaluate alternative designs during 12 the development of a system. A multitude of Design-Space Exploration 13 14 (DSE) techniques exist in the literature. Integration of these techniques 15 into the modelling paradigm is needed when a model-driven engineering approach is used for designing systems. To a greater or lesser extent, 16 the integration of those different DSE techniques share characteristics 17 with each other. Inspired by software design patterns, we introduce an 18 initial pattern catalogue to categorise the embedding of different DSE 19 techniques in an MDE context. We demonstrate their use by a literature 20 survey and discuss the consequences of each pattern. Finally, we demon-21 strate the application of our initial pattern catalogue on two examples. 22

# 23 1 Introduction

Model-Driven Engineering (MDE) uses abstraction to bridge the cognitive gap 24 between the problem space and the solution space in complex software system 25 problems. To bridge this gap, MDE uses models to describe complex systems 26 at multiple levels of abstraction, using appropriate modelling formalisms. Model 27 transformations play a key role in MDE to manipulate models. Transformations 28 are used for code synthesis, mapping between models at the same or multiple 29 levels of abstraction, etc. Model transformation is even regarded as the "heart 30 and soul of model-driven software and system development" [1]. 31

While designing a system, the need often arises to explore different design alternatives for a specific problem. Design Space Exploration (DSE) is an automatic process where possible alternatives of a particular design problem are explored. The exploration is guided with imposed constraints and optimality criteria on the different candidate solutions. In the literature a multitude of design-space exploration techniques are available, for example (Mixed Integer) Linear Programming, evolutionary algorithms and constraint satisfaction.

In our experience with embedding DSE in a model-driven engineering context 39 and a survey of the literature, we observed the use of different models, expressed 40 using different formalisms, for both design, exploration and the modelling of 41 goal functions. Combining the different models, using transformations, with the 42 multitude of techniques available for searching design-spaces revealed similarities 43 between the models and transformations of the different exploration techniques. 44 To consolidate this knowledge, we organise these methods into an *initial pattern* 45 *cataloque*, inspired by software design patterns. The goal of this effort is to create 46 a more complete pattern catalogue for model-driven engineering approaches for 47 design-space exploration with the support of the community. 48

The remainder of this paper is structured as follows. Related work is elaborated in Section 2. Section 3 introduces the Initial Pattern Catalogue. In Section 4, we discuss other useful techniques for DSE in an MDE context. Finally, Section 6 concludes our contributions and elaborates on future work. This technical report discusses some case studies, as an elaboration of our work presented in [2].

# 55 2 Related Work

The concept of patterns is widely used in Software Engineering. They provide 56 generalized solutions to common software problems in the form of templates. 57 The templates can be used by software developers to tackle the complexity in a 58 larger software problem. One of the most highly cited contributions to pattern 59 catalogues in the field of software is the work of the "Gang of Four" [3], which 60 presents various design patterns with respect to object-oriented programming. 61 Inspired by the Gang of Four, Amrani et al. [4] presents a model transformation 62 intent catalogue which identifies and describes the intents and properties that 63 they may or must possess. Their catalogue can be used for several purposes such 64 as requirements analysis for transformations, identification of transformation 65 properties and model transformation language design. Their presented catalogue 66 is a first attempt to introduce the concept of patterns in MDE. 67

A more in-depth literature study is integrated in Section 3 such that each pattern is illustrated by known uses. This motivates one to the application of the introduced patterns.

# 71 3 Initial Pattern Catalogue for DSE

In this section we first discuss the need for a pattern catalogue specific to the
Design Space Exploration domain. Next, our proposed pattern structure is described by analogy with the seminal work of the "Gang of Four" [3]. Finally,
Subsections 3.2 and 3.3 will elaborate our *initial pattern catalogue*.

### <sup>76</sup> 3.1 The need for patterns

By definition design patterns are used to formalise a problem which recur repeatedly. They help a designer to evaluate alternatives for a given design problem

in order to choose the most appropriate design. The usefulness of such patterns 79 has already been proven in the Software Engineering domain where the "Gang 80 of Four" [3] gave impetus to the creation of a widely accepted software design 81 patterns catalogue. The successful impact of its widespread use is undoubtedly 82 the well defined structure of each pattern. More specifically, each pattern is 83 typed by: (1) Pattern Name and Classification, (2) Intent, (3) Also Known as, 84 (4) Motivation, (5) Applicability, (6) Structure, (7) Participants, (8) Collabora-85 tions, (9) Consequences, (10) Implementation, (11) Sample Code, (12) Known 86 Uses and (13) Related Patterns. Each of these sections is textually described and 87 where necessary graphically supported using Class Diagrams, describing struc-88 ture, and/or Activity Diagrams, describing the workflow of the pattern. At least 89 one case study demonstrates how the patterns can be applied in practice. 90

In accordance to software design patterns, we define the format of each pro-91 posed pattern as follows. Intent: Gives a short explanation of the intention of 92 the pattern. Structure: Describes the general structure of the pattern. Con-93 sequences: Describes the trade-offs in using the pattern. Known Uses: Lists 94 the applications of the pattern in the literature. While this is not meant to be an 95 exhaustive literature review of all the applications of the pattern, one can draw 96 inspiration from these examples to apply the pattern. **Application:** Gives a 97 short description in which cases this pattern can be useful and how it can be 98 implemented. 99

The *Structure* is graphically supported by the Formalism Transformation 100 Graph and Process Model (FTG+PM). The left side of the FTG+PM clearly 101 shows all involved formalisms (boxes) and their relations using model transfor-102 mations (circles). The right side shows the process with the involved models 103 (boxes), transformed by a model transformation (roundtangle). Complex data-104 flow (dashed line) and control-flow (full line) relations can exist in the process 105 part of the FTG+PM. This can be summarized as a legend, which is shown 106 in Figure 1. The reason behind this latter supported formalism is threefold: 107 (1) It clearly represents the structure of the approach by connecting the dif-108 ferent formalisms with transformations on the left side of the FTG+PM. The 109 FTG+PM also shows the workflow of combining the different models and trans-110 formations in a process on the right side. (2) The FTG+PM can be used to (semi-111 )automatically execute the defined transformation chains (yellow coloured). Man-112 ual operations are also possible that allow for experience based optimisation and 113 design (grey coloured). (3) Different patterns described in this formalisms are 114 easily connected to each other. This enables the embedding of DSE within the 115 MDE design of systems. 116

As mentioned in section 1, we would like to refer to our technical report [2] where we apply our *initial pattern catalogue* to some case studies.

### 119 3.2 Exploring Design Spaces

Performing design-space exploration in a model-driven engineering context can
be abstracted in some steps: (1) A meta-model defines the structural constraints
of a valid solution. (2) A DSE-tool generates valid candidate solutions conforming



Fig. 1: FTG+PM Legend

to the meta-model. An initial model adds other structural constraints to the set 123 of candidate solutions. (3) A transformation transforms the set of candidate 124 solutions to an analysis formalism to check the feasibility of the solution with 125 respect to a set of constraints. (4) If necessary, a second transformation generates 126 a model in a performance formalism to check the optimality of the solution 127 with respect to certain optimisation goals. (5) Depending on the optimisation 128 technique, the process is iterated multiple times. Information from feasibility 129 and performance models is used to guide the exploration. 130

Depending on the exploration technique, we classify different model-driven 131 engineering approaches to solve this generic design-space exploration strategy. 132

Model Generation Pattern 133

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Fig. 2: Model Generation Pattern

**Intent:** This pattern transforms the meta-model of a problem space together 135 with constraints to a constraint-satisfaction problem. The exploration of the 136

design consists of the generation of a set of models that satisfy the structural 137

constraints imposed by the meta-model and the other constraints provided usinga constraint formalism.

Structure: The pattern, shown in Figure 2, starts with a meta-model and 140 some constraints. A transformation transforms these models into a constraint 141 satisfaction problem. By invoking a solver, an exploration of the design space 142 generates candidate solutions. Each candidate solution is transformed into an 143 analysis representation. The analysis produces traces of each candidate solution. 144 Based on the goal function model, the optimal trace is transformed to a solution 145 model. This solution model can either be expressed in the exploration formalism, 146 the original model formalism or a specific solution formalism. 147

**Consequences:** Depending on the used solver, this method might be com-148 putationally and memory intensive because an exhaustive search of the design 149 space is executed. A transformation is needed to translate the meta-model with 150 constraints to a model that is usable by the DSE-tool. Domain knowledge can 151 be introduced by adding constraints to the meta-model. Note that adding extra 152 constraints helps the search for a solution. An initial model, where some choices 153 are predetermined, adds extra constraints. A less generic alternative is to add 154 the initial model when evaluating candidate solutions. 155

**Known Uses:** Neema et al. [5] present the DESERT framework used for Model-156 Driven constraint-based DSE. It implements an automated tool which abstracts 157 the Simulink design space to generate candidate solutions. In [6] the FORMULA 158 tool is presented, where candidate solutions are generated from a meta-model. 159 A similar tool called Alloy is used by Sen et al. [?] to automatically generate 160 test models. Saxena and Karsai [7] present an MDE framework for generalized 161 design-space exploration. A DSE problem is constructed out of a generalized 162 constraint meta-model combined with a domain specific meta-model. 163

Application: The pattern is not recommended when one searches for an opti mal solution out of a large search space without a lot of constraints. On the other
 hand, this pattern is very useful to rapidly obtain candidate solutions conforming
 to the meta-model.

#### <sup>168</sup> Model Adaptation Pattern

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Intent: This pattern transforms the model or a population of models to a
generic search model used in (meta-) heuristic searches. Depending on the problem and search algorithm, different search representations can be used.

**Structure:** A model or population of models expressed in a certain formalism is transformed to a specific exploration formalism. Based on the guidance of a goal function, an algorithm creates new candidate solutions. A (set of) candidate solutions are transformed to an analysis model in order to evaluate. Finally, the result is transformed to a solution model. This solution model can either be expressed in the exploration formalism, the original model formalism or a specific solution formalism.

Consequences: A dedicated search representation has to be created as well as
 manipulation functions to create alternative designs. This requires an adequate
 understanding of the problem and domain knowledge. A translation from the



Fig. 3: Model Adaptation Pattern

problem domain to the search representation and vice-versa is required. An initial
model, as a constraint, can be added by fixing the generated solution or by
rewriting the functions to create new solutions (cross-over, mutation, etc.).

Known Uses: Williams et al. searched for game character behaviour using a 186 mapping to a genetic algorithm [8]. Burton et al. solve acquisition problems using 187 MDE [9]. Genetic algorithms are used to create a Pareto front of solutions. A 188 stochastic model transformation creates an initial population. Finally, Kessentini 189 and Wimmer propose a generic approach to searching models using Genetic 190 Algorithms [10]. The proposed method is very similar to the described pattern. 191 Application: This pattern is recommended when a design problem can easily 192 be transformed to an optimal search representation, e.g. a list or tree repre-193 sentation. Different operations on this new representation are implemented in 194 the solution space (usually a generic programming language). Well-known algo-195 rithms, like genetic algorithms and hill-climbing, implement the search. 196

## <sup>197</sup> Model Transformation Pattern

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Intent: This pattern uses the original model to explore a design-space. Model 199 transformations encode the knowledge to create alternative models. Guidance to 200 the search can be given by selecting the most appropriate next transformation 201 or by adding meta-heuristics to the model transformation scheduling language. 202 Structure: A model combined with a goal function is used to create a set of 203 candidate solutions that are expressed in the original model formalism. These 204 are transformed to an analysis representation to gather some metrics that are 205 expressed by a trace. Using (meta-)heuristics, a new set of candidate solutions 206



Fig. 4: Model Transformation Pattern

can be generated according to a goal function. Finally, if required, the most
optimal solution or set of solutions can be transformed into a solution model.

Consequences: A high degree of domain knowledge about the problem is re-209 quired to design the transformation rules. On the other hand, the rules encode 210 domain knowledge to guide the exploration. Model-to-model or model-to-text 211 transformations are required to evaluate a candidate solution. An initial model 212 as a constraint can be added by adjusting the meta-model with variation tags. 213 Similarly to the *Model Adaptation Pattern*, the initial conditions can also be 214 implemented as fix operations using model transformations. Model transforma-215 tions to create new candidate solutions are computationally expensive because 216 of the subgraph isomorphism problem. 217

Known Uses: In [?] a model-driven framework is presented for guided design space exploration using graph transformations. The exploration is characterised by a so called exploration strategy which uses hints to identify dead-end states and to order exploration rules. This way the number of invalid alternatives is reduced. Denil et al. [11] demonstrates how search-based optimization (SBO) techniques can be included in rule-based model transformations.

Application: The pattern is used when it is hard to obtain a generic search representation. Model transformation rules, expressed in the natural language of the engineer, are implemented using current model transformation tools. Guidance is implemented through the scheduling of the model transformation rules.

### 228 3.3 Exploration Chaining Pattern

In order to prune the design space more efficiently, multiple of the proposed patterns can be chained. This technique is called "Divide and Conquer" and may as
well be described by a pattern. To represent the chaining of multiple FTG+PMs,
this pattern is graphically supported by means of a principle representation.

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<sup>234</sup> Intent: This pattern adds multiple abstrac-

 $_{\rm 235}$   $\,$  tion layers in the exploration problem where

candidate solutions can be pruned. High-level
estimators are used to evaluate the candidate
solutions and prune out non-feasible solutions

and solutions that can never become optimal

<sup>240</sup> with respect to the evaluated properties. Fig-

<sup>241</sup> ure 5 shows the overall approach of this pat-<sup>242</sup> tern.

**Structure:** At each of the abstraction layers



Fig. 5: Exploration Chaining Pattern

an exploration pattern is used to create and evaluate candidate solutions. Non pruned solutions are explored further in the next exploration step.

Consequences: Domain knowledge about the problem is required to add levels of abstraction. High-level estimators are needed at each of the abstraction layers to evaluate a candidate solution. Because more information is introduced at each of the abstraction layers, the evaluation of a single candidate solution becomes more complex and usually more computationally intensive. Finally, a pruning strategy is required to decide what solutions have to be pruned at each of the abstraction layers.

Known Uses: Sen and Vangheluwe add different levels of abstraction in the design of a multi-domain physical model [12]. This numerically constraints the modeller to create only valid models. Kerzhener and Paredis introduce multiple levels of fidelity in [13]. Finally, multiple levels of abstractions for an automotive allocation and scheduling problem are introduced in [14].

Application: This pattern provides a solution when memory and time complexity are an issue during the exploration of the design space. It tackles the complexity by its layered pruning approach. Therefore, this pattern is preferred when searching for (an) optimal solution(s) in a large search space. Different exploration patterns are chained to create solutions.

# 263 4 Discussion

In this section we describe some other techniques that are useful for design space exploration in a model-driven engineering context. Some techniques could
 potentially become a pattern in a new version of the catalogue.

Dealing with Multiple Objectives : Multi-objective optimisation deals with the
 decision making process in the presence of trade-offs between multiple goal func tions. Certain DSE and search algorithms can deal with multi-objective functions

by construction. However, some techniques do not have this features. Here wegive two ways of dealing with the problem.

Scalarize the Objective-Function: When scalarizing a multi-objective optimisation problem, the problem is reformulated as a single-objective function. The goal function model becomes a combination of individual objective functions. A model defines how the combination of the different individual goal function models is done, for example in a linear fashion, or other more complex functions.

Create Variants: In certain cases the designer would like to compare
the different trade-offs using a Pareto curve. We use the scalarizing pattern to
create multiple variants of the combined objective function. Intermediate results
of the exploration are used to select an appropriate recombination that could
potentially add a new Pareto solution.

Meta-model reduction: By using sensitivity analysis of the involved modelling elements and parameters, the meta-model can be reduced with the elements and parameters that have a small influence on the result of the goal function. An example of this technique can be found in [15].

### 287 5 Examples

In this section we illustrate the implementation of the previously described patterns by means of two examples. The first example searches for an electrical filtering circuit. The second example is a resource allocation problem in the automotive domain based on [16].

#### <sup>292</sup> 5.1 Electrical Network

We regard a filter design as a black box with an input, output and mass node 293 with some passive electrical components in between which are connected to each 294 other. When focussing on the exploration of passive analogue filters, those electri-295 cal components can be *Resistors*, *Capacitors* and *Inductors*. The corresponding 296 meta-model is shown in Figure 6. Various configurations of those components 297 lead to the construction of different types of filters. An example is a Low-Pass 298 Filter (LPF) which passes low-frequency signals and attenuates signals with fre-299 quencies higher than the cut-off frequency ( $\omega_c$ ). A filter its behaviour is specified 300 using a gain-magnitude frequency response, also called Bode plot, whereof an 301 example is shown in Figure 7. 302

The goal of our DSE is to find a filter where its Bode plot has a minimal deviation compared to the theoretical one shown in Figure 7. Therefore, we see the deviation as a difference value between the theoretical and measured gain for each frequency point. In that case, the goal-function or fitness-function can be formulated by Equation 1. A larger deviation will result in a higher score, while a solution containing fewer components will result in a lower score.



Fig. 6: Meta-model of a passive electrical design filter



Fig. 7: LPF Bode plot

Which pattern of our proposed *initial pattern catalogue* can one apply to 309 solve this design problem? Since the search space is quite large without a lot 310 of constraints, we exclude the model generation pattern. This implementation 311 has a very high memory and time complexity, resulting in a uncompleted ex-312 ploration of the design space and thus a non-optimal solution. When choosing 313 the *dedicated search representation* pattern, one will notice we are dealing with 314 a design problem which is hard to transform to a generic search model such as 315 a list or tree. The most appropriate pattern to implement this design problem 316 is the search using model transformation pattern. The designer has to create a 317 set of model transformation rules that apply mutation operations on the initial 318 model. Example of such search rules are: adding or removing a serial or parallel 319 connections, etc. 320

#### 321 5.2 Allocation Problem

In the second example, we have a set of communicating software functions which 322 need to be assigned to a set of Electronic Control Units (ECUs) connected by 323 a communication bus. An example of such an allocation problem is shown in 324 Figure 9. The corresponding meta-model is shown in Figure 8. It contains a 325 SWC (Software Component) with a Name, a Period and a WCET (Worst Case 326 Execution Time) describing the maximum time a task could be executed on a 327 specific ECU. A SWC can be mapped to a single ECU. When a SWC is mapped 328 to an ECU the Load attribute of the ECU is increased by (WCET/Period) of 329 the mapped software function. A similar calculation is used for the Load on the 330 Bus, based on the Size of the communication messages (*Comm*) and the Period 331 of the sending software function. The Load on the Bus only increases when the 332 sending and receiving SWC are mapped to a different ECU. 333



Fig. 8: Meta-model of the allocation problem



Fig. 9: Example of an allocation problem

Zheng et al. [16] approach the problem by searching for a mapping where the 334 total load of the different ECUs are below a threshold of 69% (the schedulability 335 test for rate-monotonic systems [17]). The goal-function or fitness-function for 336 finding an optimal solution is to minimise communication between the different 337 ECUs because the communication on the bus introduces delays that impact 338 the timing behaviour of the final solution. Therefore, the goal-function can be 339 formulated by Equation 2. The penalty for unfeasibility is one order magnitude 340 higher than the communication cost. 341

$$Score = Eff. Communication Cost + Penalty$$
(2)

This design problem lends itself for chaining two design patterns: the model 342 generation pattern followed by the dedicated search representation pattern. Since 343 the design problem can easily be transformed to a list representation, the choice 344 of the *dedicated search representation* pattern is obvious. The list index defines 345 the software component, the value defines the ECU on which the component is 346 mapped. We use a genetic algorithm with a single cross-over point to generate 347 new allocations. The preliminary model generation pattern is used for generating 348 an initial population of models. This population of models is a precondition when 349 searching for candidate solutions using Genetic Algorithms. 350

# **351 6 Conclusions and Future Work**

Resulting from our own experiences with DSE and a literature survey, we presented an initial pattern catalogue which categorizes different approaches of Model-Driven Design Space Exploration. We described the patterns by the use of the FTG+PM to visualise the involved formalisms and their relations using model transformations. We demonstrated the use of those patterns by references to the literature and by means of two examples. With the support of the community, it is our ambition to extend this towards a more complete this initial pattern catalogue, similar to the widely available software design patterns used in software engineering. Finally, we would like to investigate the parts of patterns that can be fully or partially automated.

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