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Meta-Modelling Hybrid Formalisms

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Presentation Overview

1. Domain-specific Modelling
2. HS=ES+ODE, a Hybrid Formalism
 - A simple hybrid model
 - Simulating the model
3. Meta-modelling HS
4. Model transformation
5. Conclusions

Domain-specific Modelling

- Match modellers' mental model on the problem domain
- Maximally constrain users
- Exploit domain-specific features for analysis, synthesis, . . .

HS=ES+ODE, a Hybrid Formalism

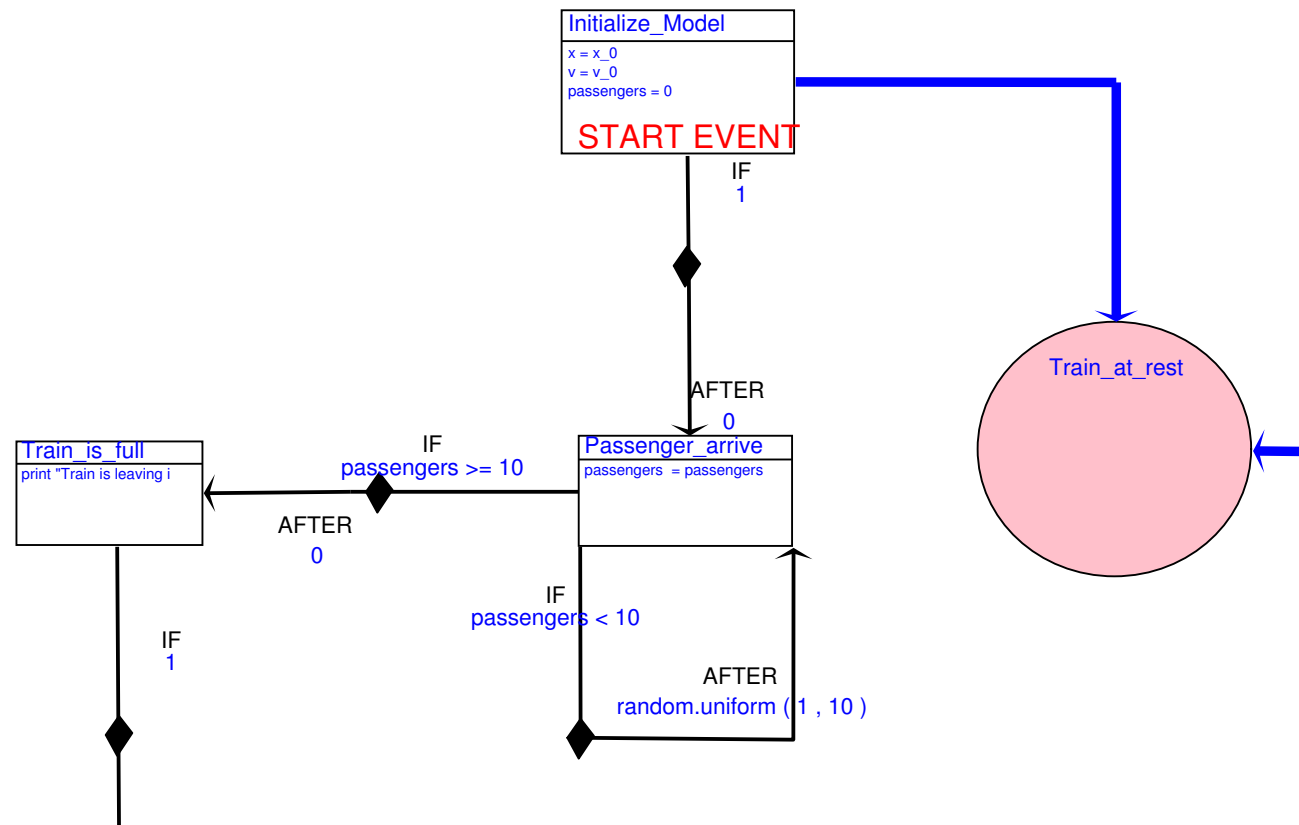
- To demonstrate the ease with which an HS-specific modelling environment can be built
- HS combines
 - Event Scheduling (ES)
to describe discrete-event behaviour
 - Ordinary Differential Equations (ODEs)
to describe continuous-time behaviour
 - Constructs to link ES and ODE

Example: Personalized Rapid Transit (PRT)

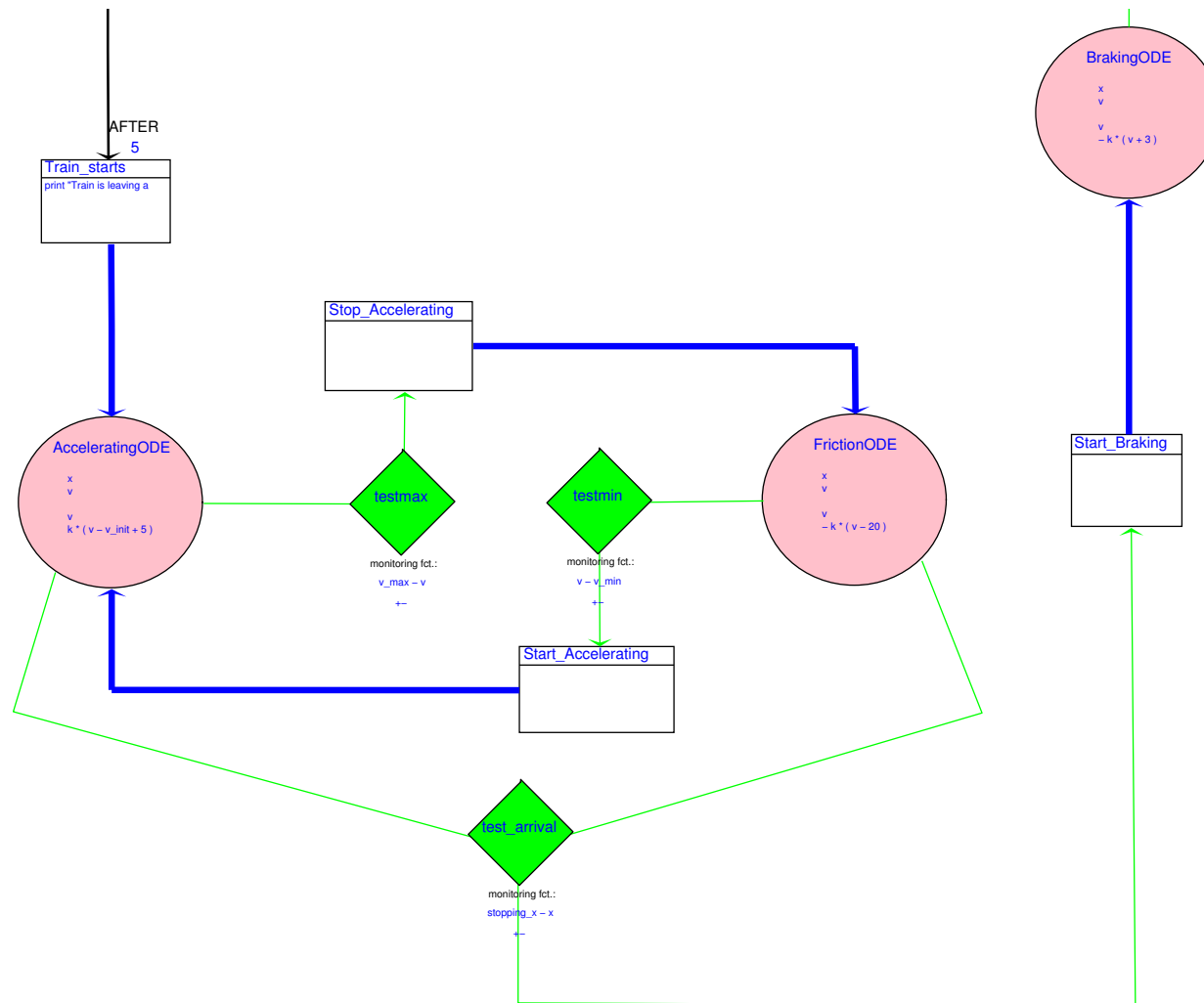


- Discrete-event behaviour: loading and unloading passengers
- Continuous-time behaviour: accelerating, decelerating
- Control: keep velocity between boundaries by switching between continuous “modes”

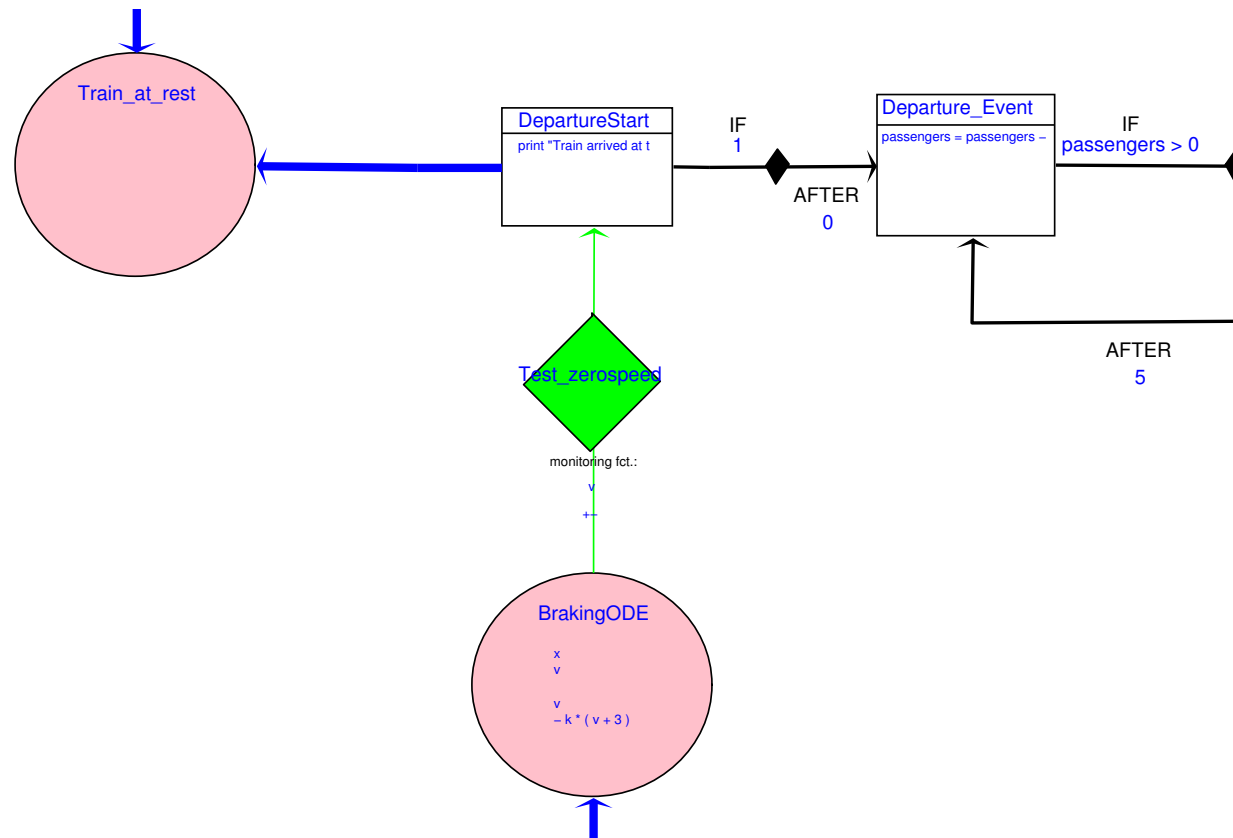
Passenger Arrival



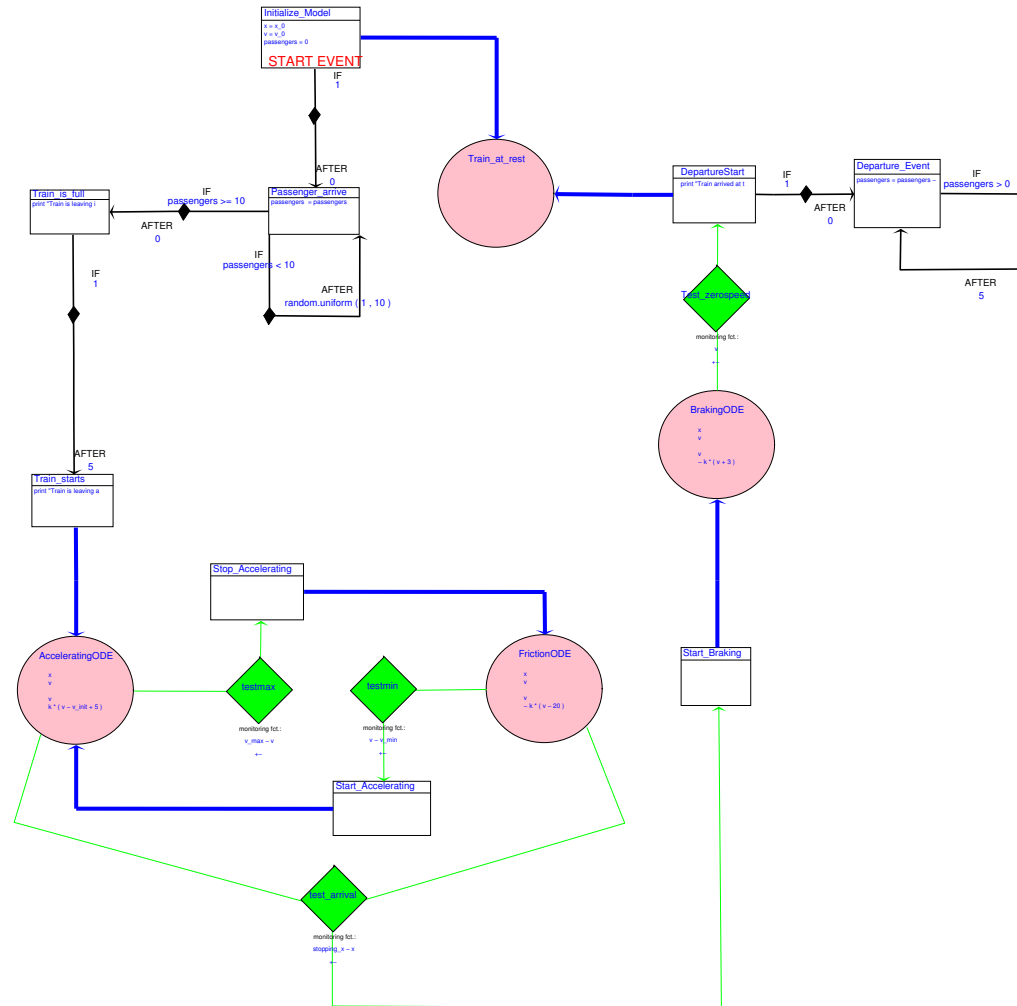
Train Motion



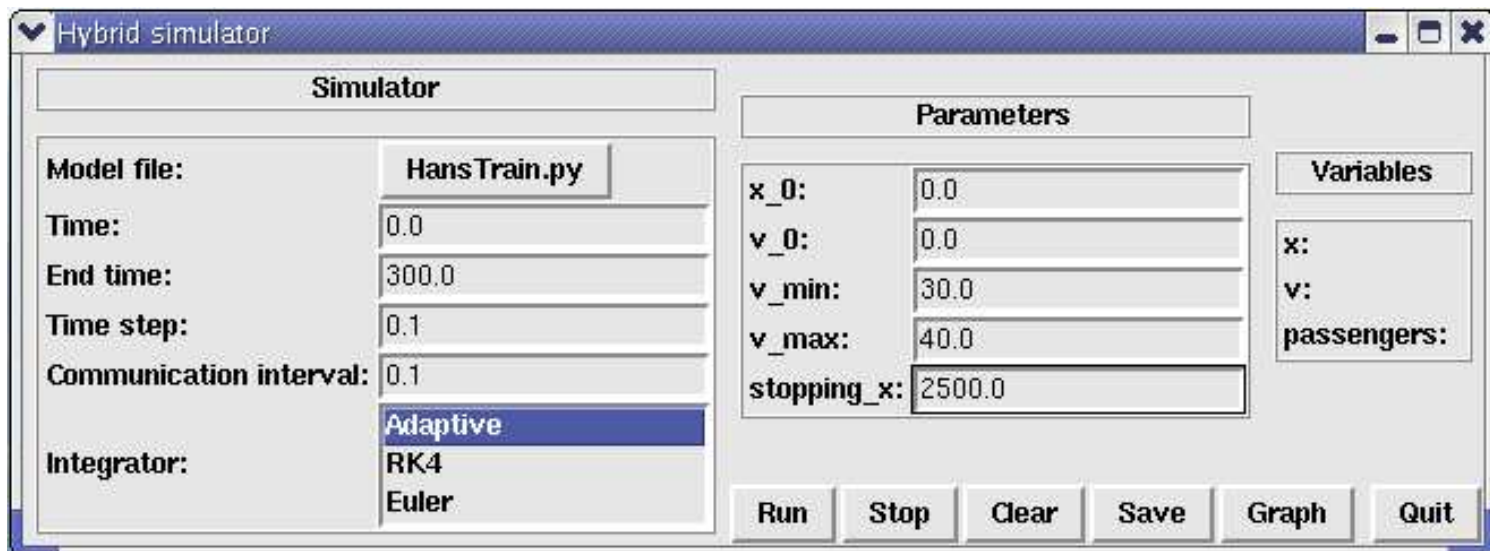
Train Arrival and Unloading



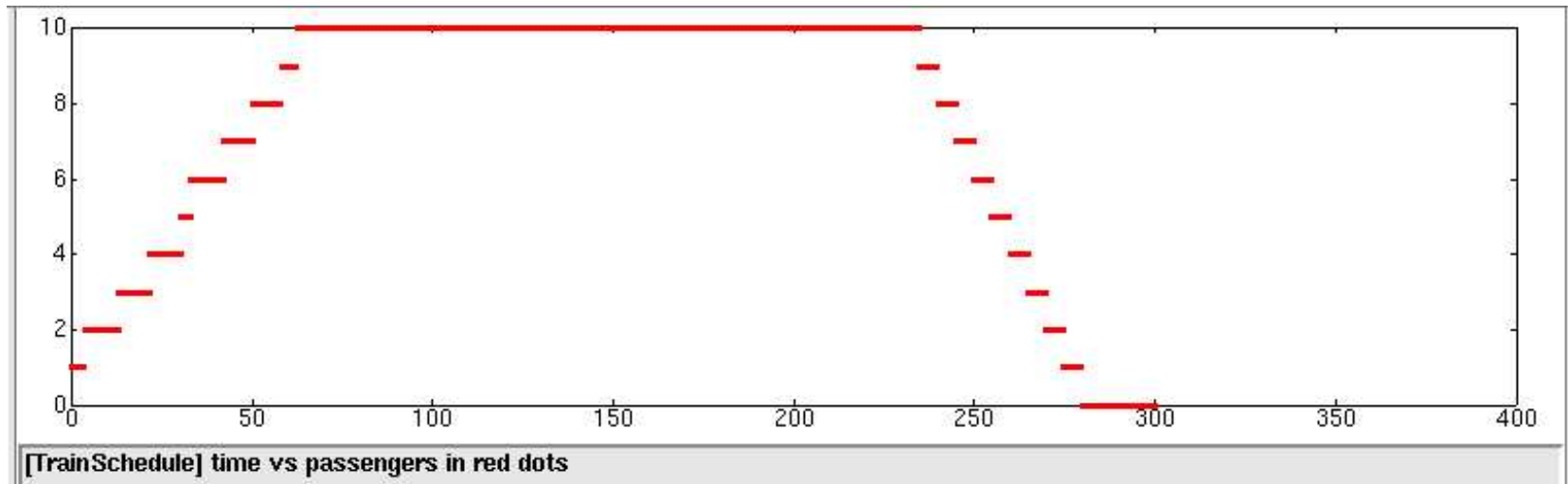
The Complete Model



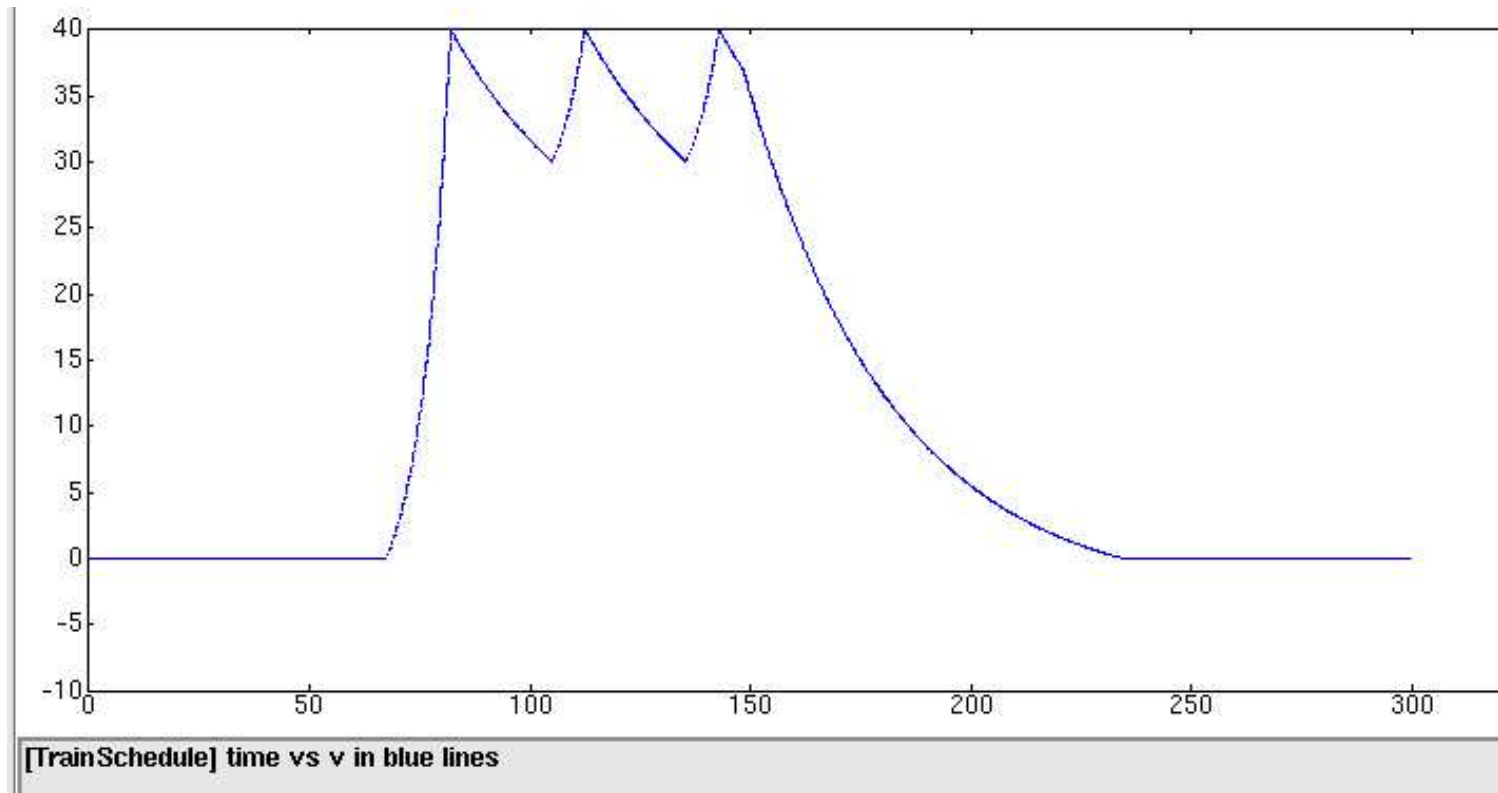
Simulating the (compiled) Model



Train Passengers



Train Velocity

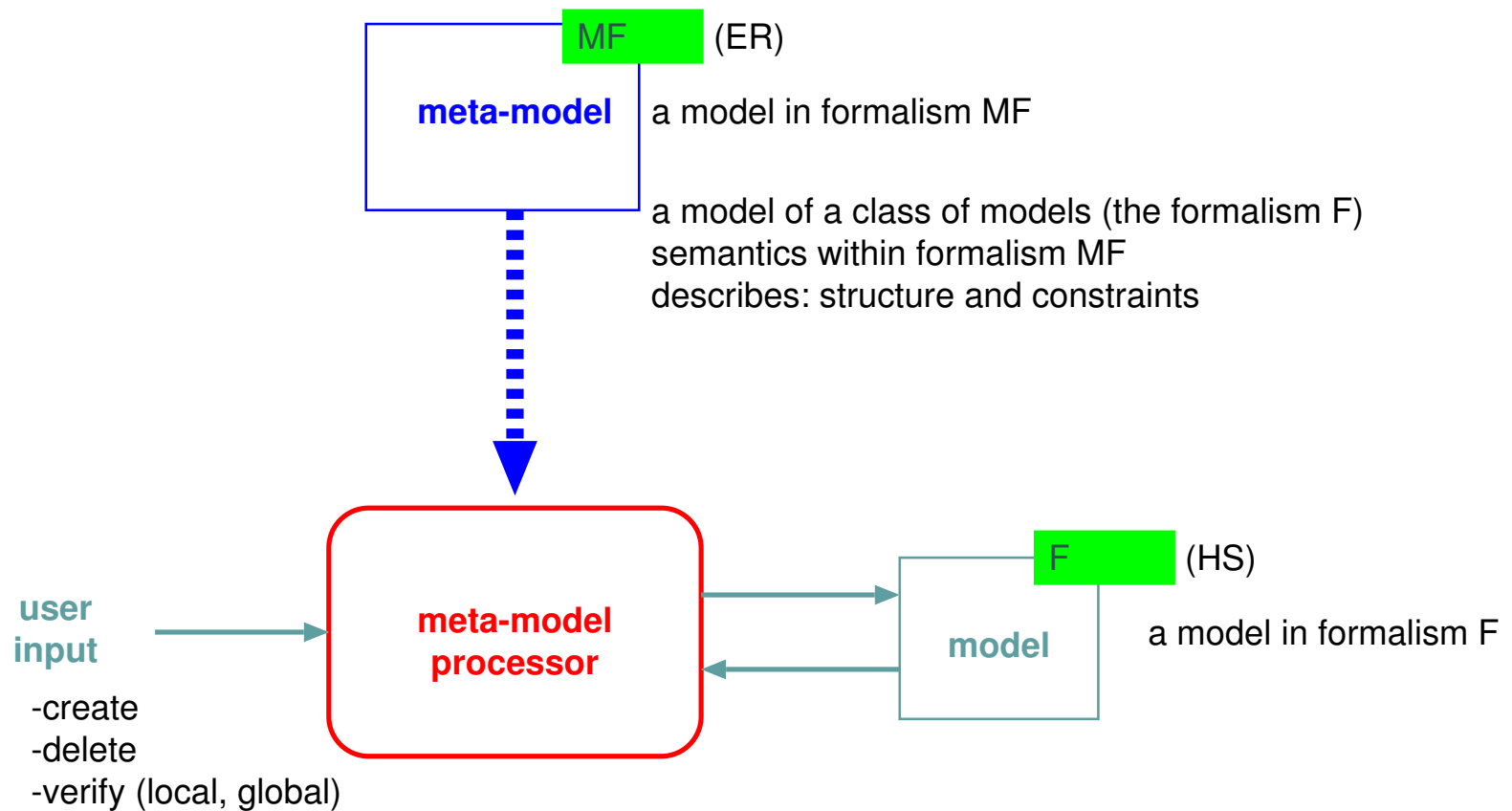


Meta-modelling (the HS formalism)

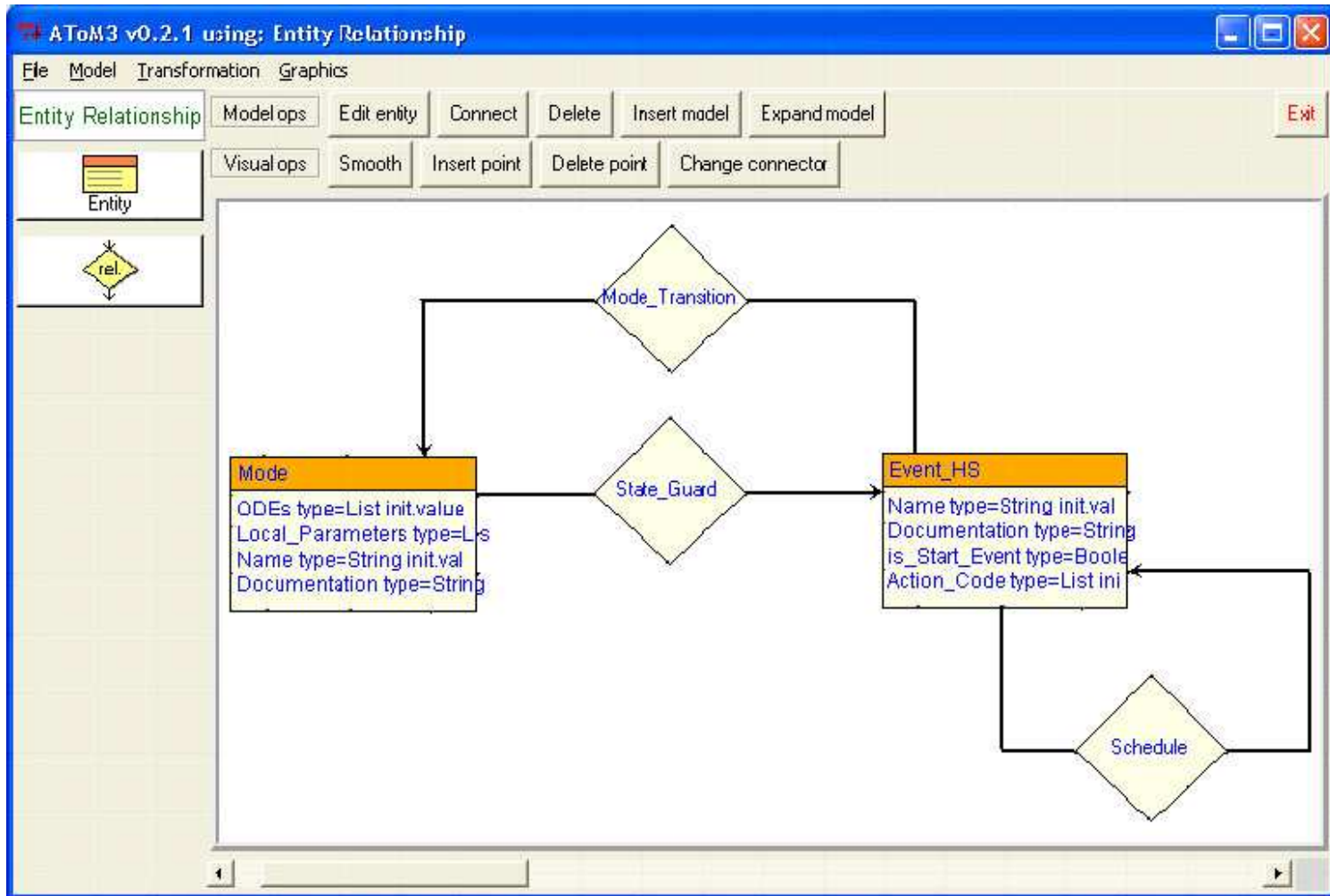
- A meta-model is **a model of** a modelling formalism
- A meta-model is itself a model. Its (textual or visual) *syntax* and *semantics* are governed by the formalism it is described in. That formalism can be modelled in a meta-meta-model.
- As a meta-model is a model, we can reason about it, manipulate it, . . . In particular, properties of (all models in) a formalism can be formally proven.
- Formalism-specific modelling and simulation tools can *automatically* be synthesized from a meta-model.

- Formalisms can be tailored to specific needs by modifying the meta-model (possibly through inheritance if specializing).
- Semantics of new formalisms can be given through extension or transformation of/between formalisms.

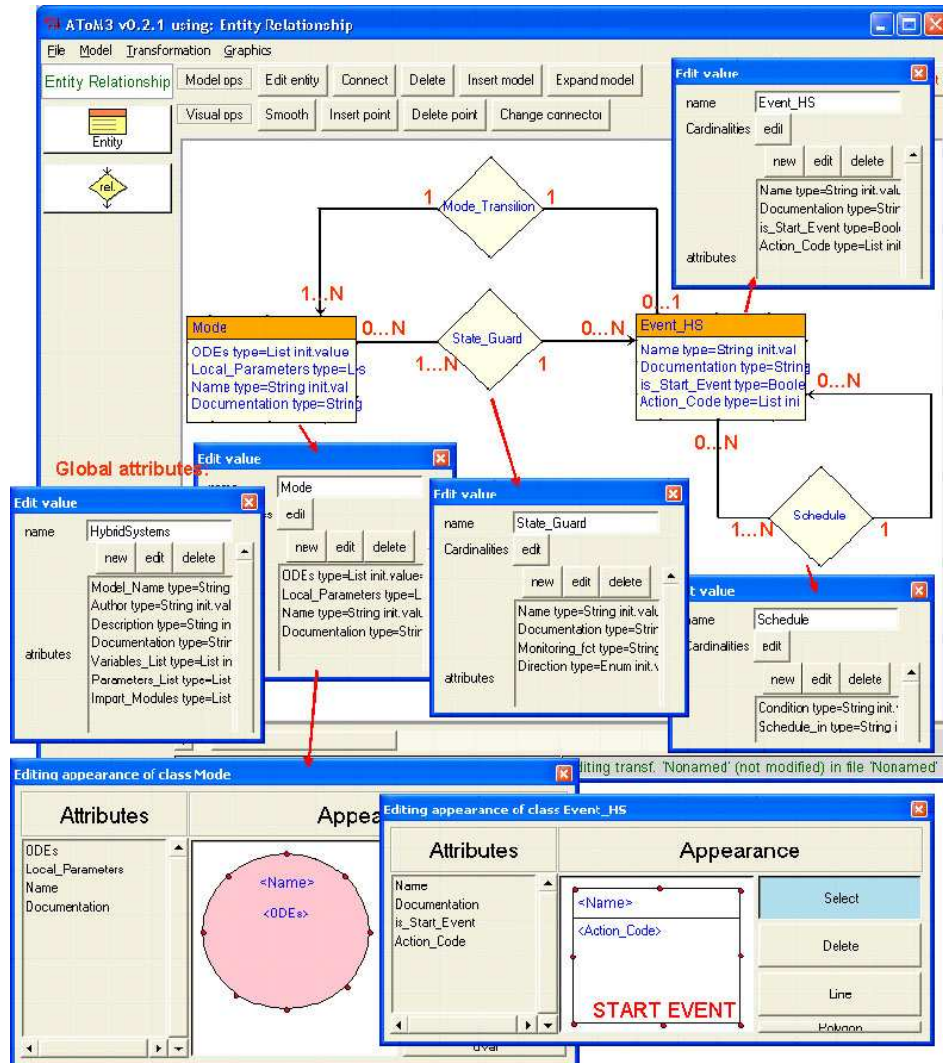
Meta-modelling



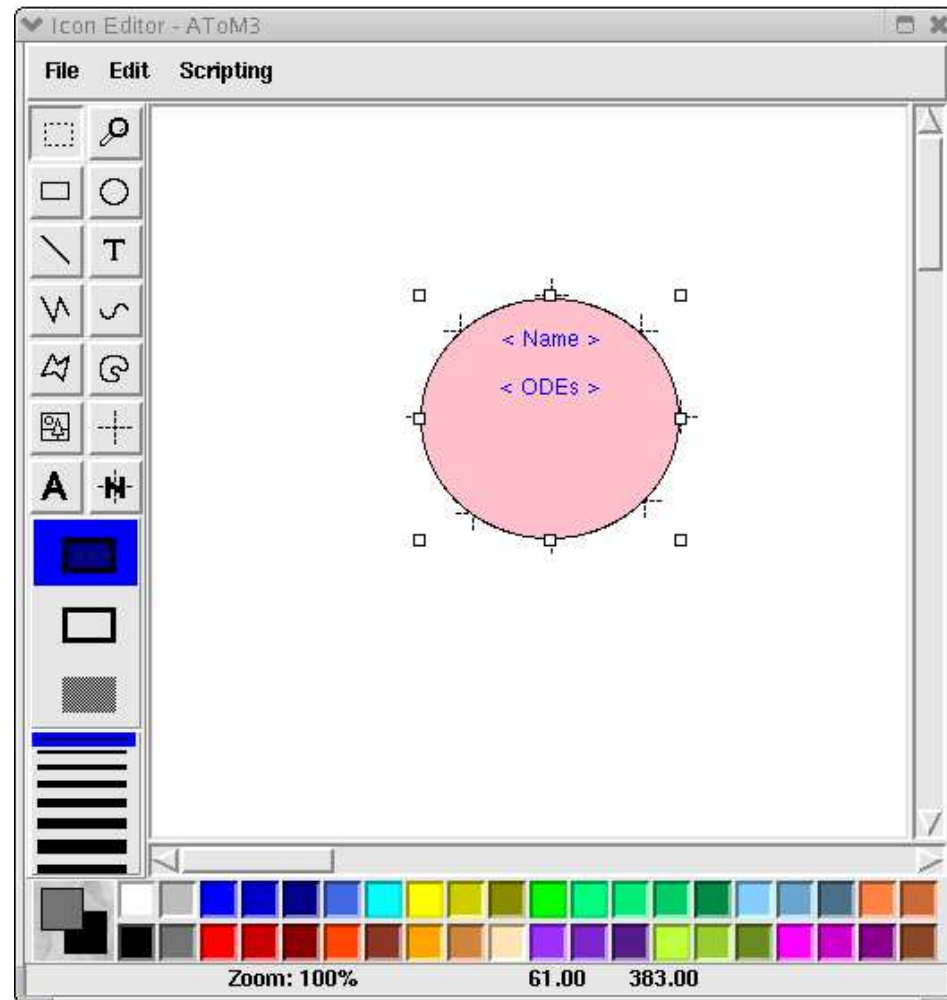
HS Meta-model



HS Meta-model Details



Editing Entity Visual Representation

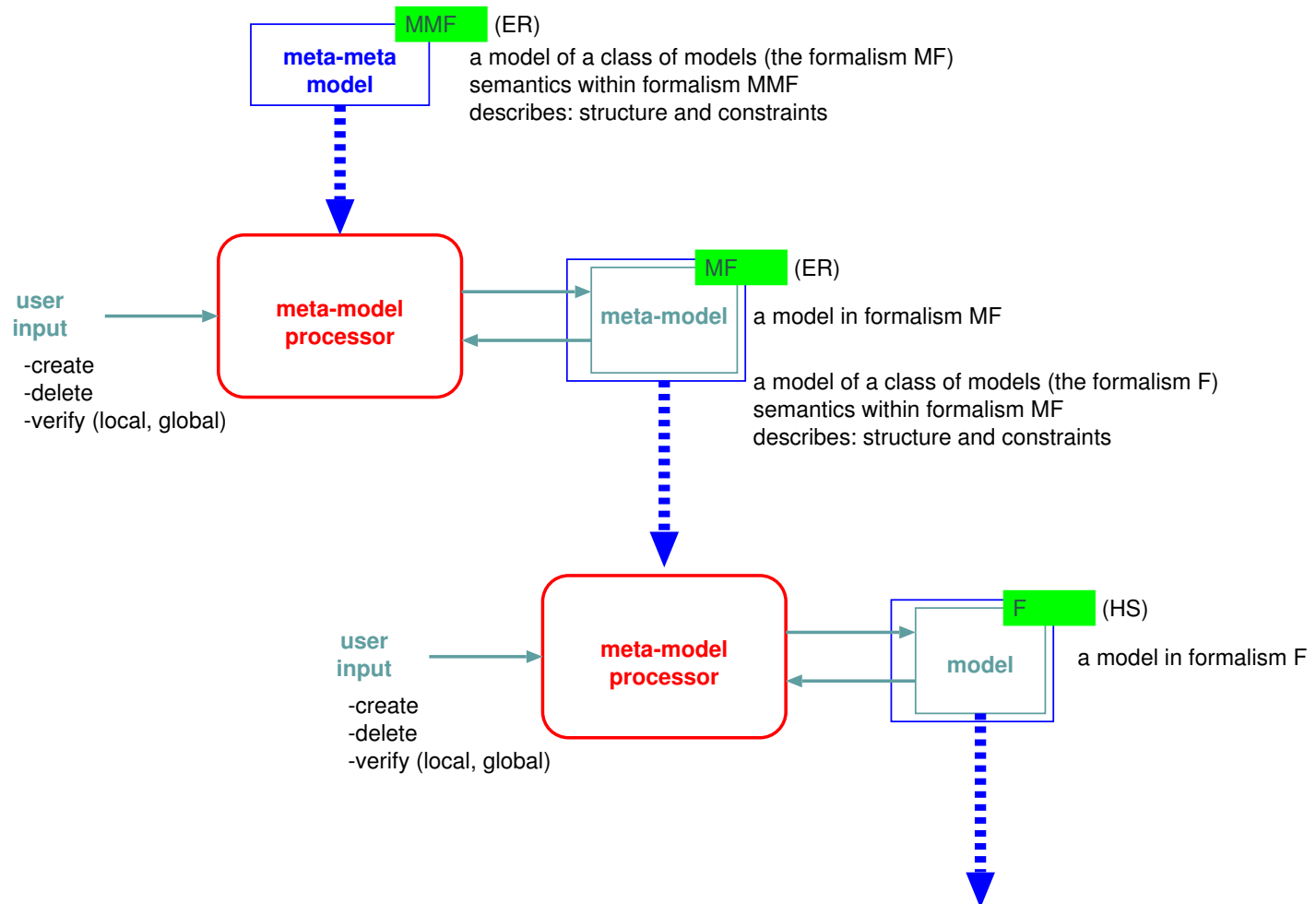


The Synthesized HS Modelling Environment

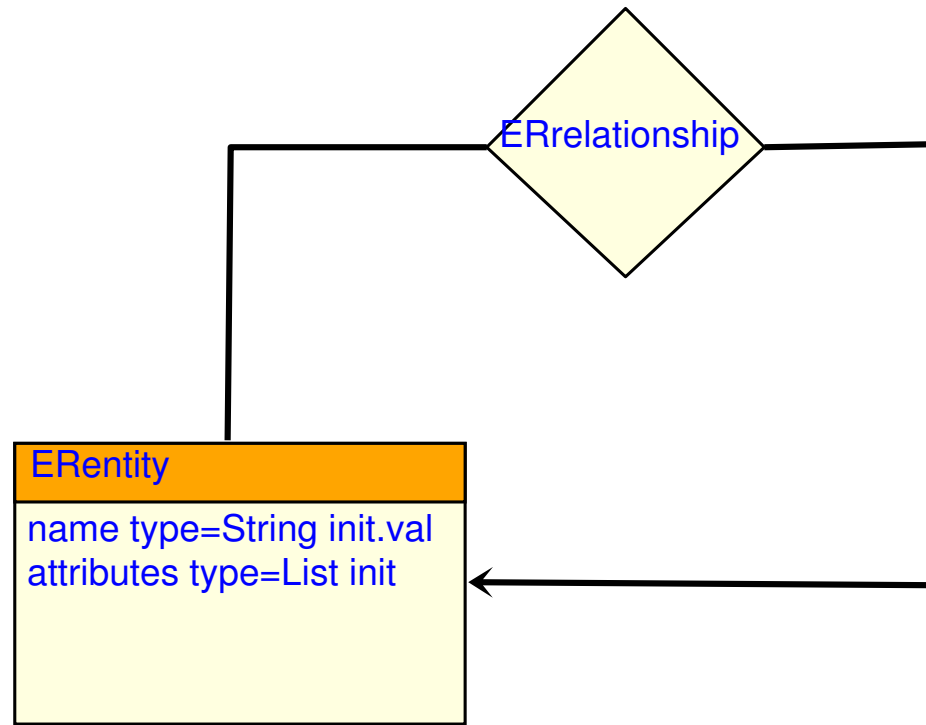
The screenshot displays the Synthesized HS Modelling Environment. The main window shows a hybrid system model with the following components:

- Global attributes:** Model Name: BouncingBallStuck, Author: SLJ, Description: A ball in free fall with inelastic collision, Documentation: This model was used to test the synthesis of a hybrid system.
- Variables_List:** y , v
- Parameters_List:** g {9.8}, y_0 {100.0}, v_0 {3.0}, k {0.95}, t_stuck {80.0}
- HS Diagram:**
 - Initialize_Model:** Action with guard $y = y_0$ and $v = v_0$.
 - Free_Ball:** State with variables y and $-g$.
 - Check_Collision:** Event with monitoring function y and direction $+$.
 - Collision:** Local parameter with equation $v = -k * v$.
 - Schedule:** Event with condition $t > t_stuck$ and schedule in 0.
- Configuration Windows:**
 - Event HS:** Name: Initialize_Model, is_Start_Event: . Action Code: $y = y_0$, $v = v_0$.
 - State_Guard:** Name: Check_Collision, Monitoring_fct: y , Direction: $+$.
 - Schedule:** Condition: $t > t_stuck$, Schedule_in: 0.
 - Mode:** ODEs: $y' = g$, $y|v|$. Local Parameters: Name: Free_Ball.

Meta-meta-...



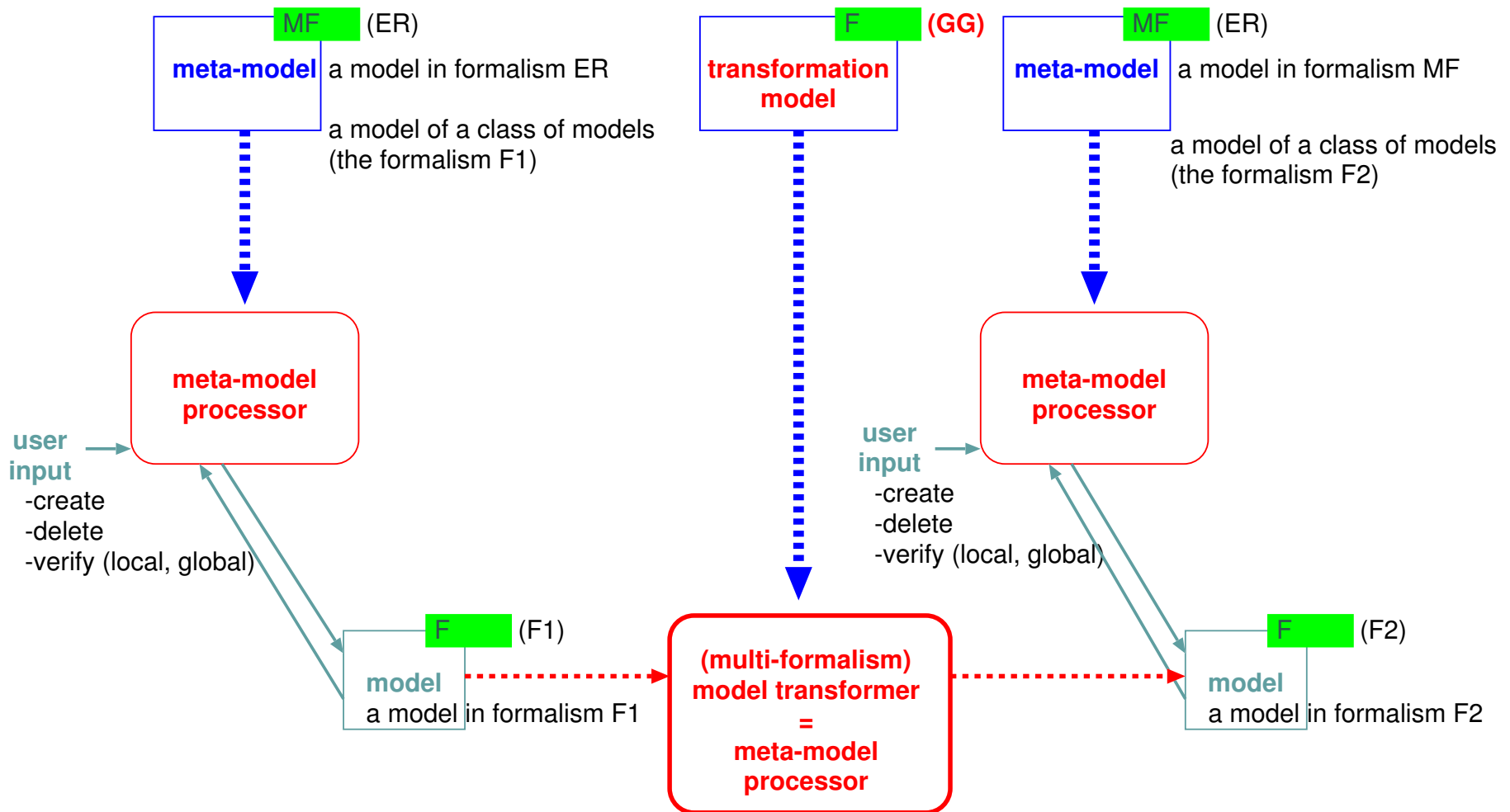
HS' meta-meta model



Transformation of Models

- Specify “operational” semantics (reference simulator)
- Specify “denotational” semantics (map onto known formalism)
- Transform between abstraction levels
- Optimize models
- ...
- *Model* transformation in the Graph Grammar formalism

Model Transformation Specification



Conclusions

- Meta-modelling, with appropriate tool support, allows building formalism/domain-specific (visual) modelling environments in record time
- \Rightarrow no reason to NOT use “tailored” formalisms
- AToM³ is A Tool for Multi-formalism and Meta-Modelling
`atom3.cs.mcgill.ca`
- Graph Grammars to explicitly model *transformations*