Modeling syntax and semantics of πDemos in AToM^3

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August 28th, 2006

Overview

- πDemos, the article
  - Context
  - Structure
- Modeling the syntax: The Meta-Model
  - Modified structure
  - Time
- Modeling the semantics: Graph Grammars
  - Rules

- Words in action…

Introduction

- G. Birtwistle: Calgary, Canada

  C. Tofts: Swansea, Wales

- Operational semantics of process-oriented simulation languages – Part 1: πDemos, 1993

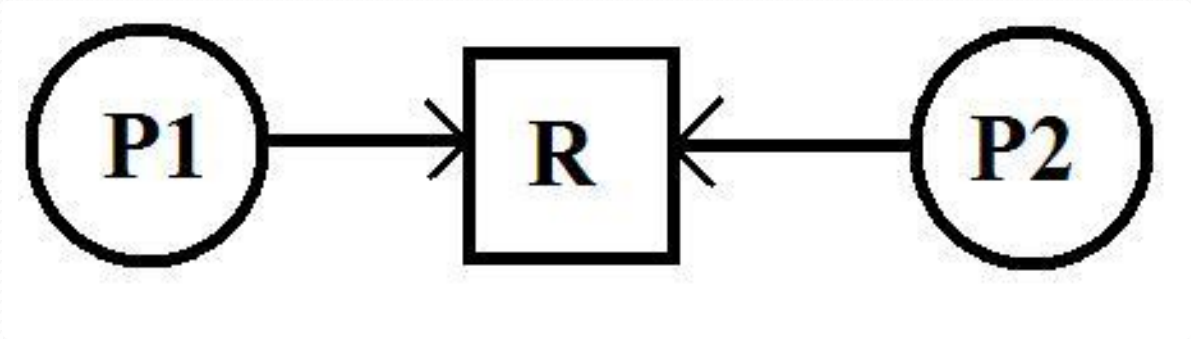
What is πDemos?

- **πDemos** is a small process-oriented discrete event simulation language. It is a TEXTUAL language

- **πDemos** operational semantics enables a complete control on
  - Synchronization
  - Event-list scheduling
  - Inter-process communication

πDemos' structure

- Process vs Resource



πDemos' structure

- Process vs Resource

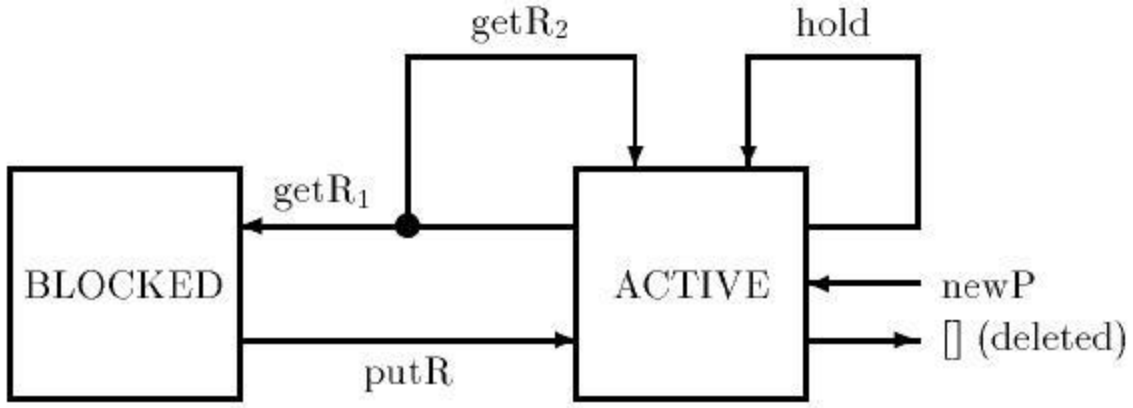


Figure 1: The ways processes change state

That’s all nice, but…

```
EL = [ (MAIN, PD([hold(6),hold(0),close],  [],0)),
       (V1,   PD([getR(W),hold(3),putR(W)],[],0)),
       (V2,   PD([getR(W),hold(3),putR(W)],[],2))
     ]
```

Now let's use 2006 technology

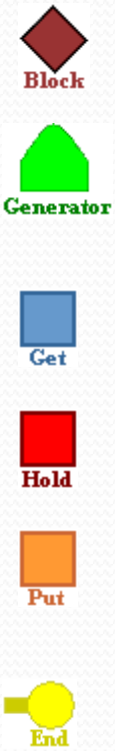
We want to model the syntax and semantics of πDemos

First, a Meta-Model

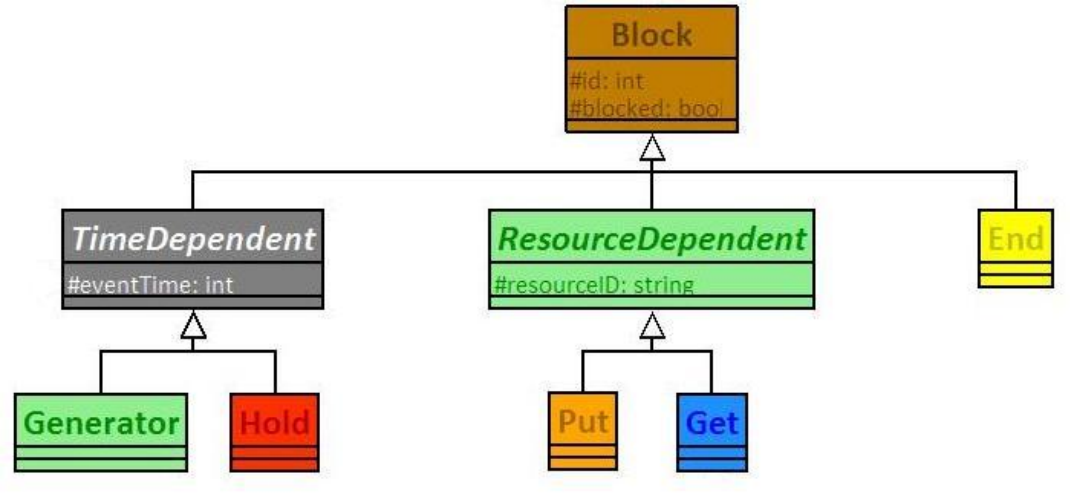
"Everything is a model"

Rules / Actions are *Blocks*

- Block
- Generator
- Get
- Hold
- Put
- End



UML class diagram



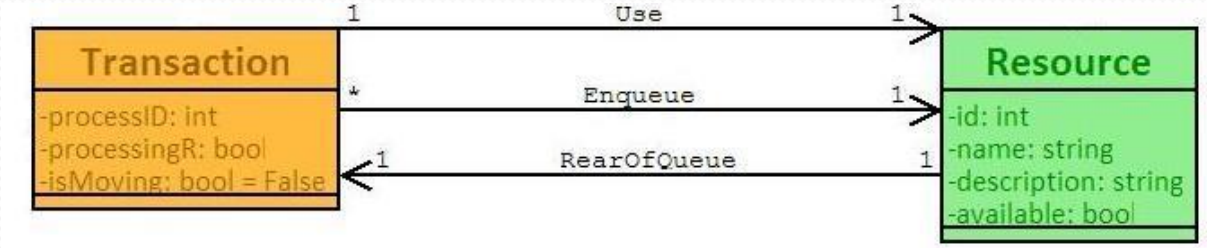
First, a Meta-Model

"Everything is a model"

Resource and transaction **UML class diagram**

- Resource

- Transaction



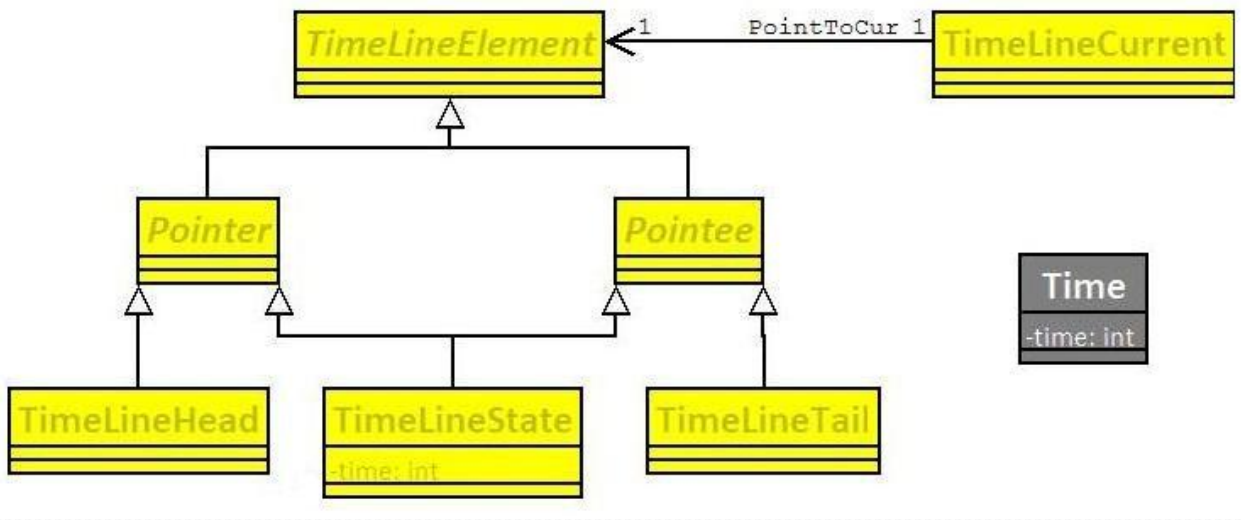
First, a Meta-Model

"Everything is a model"

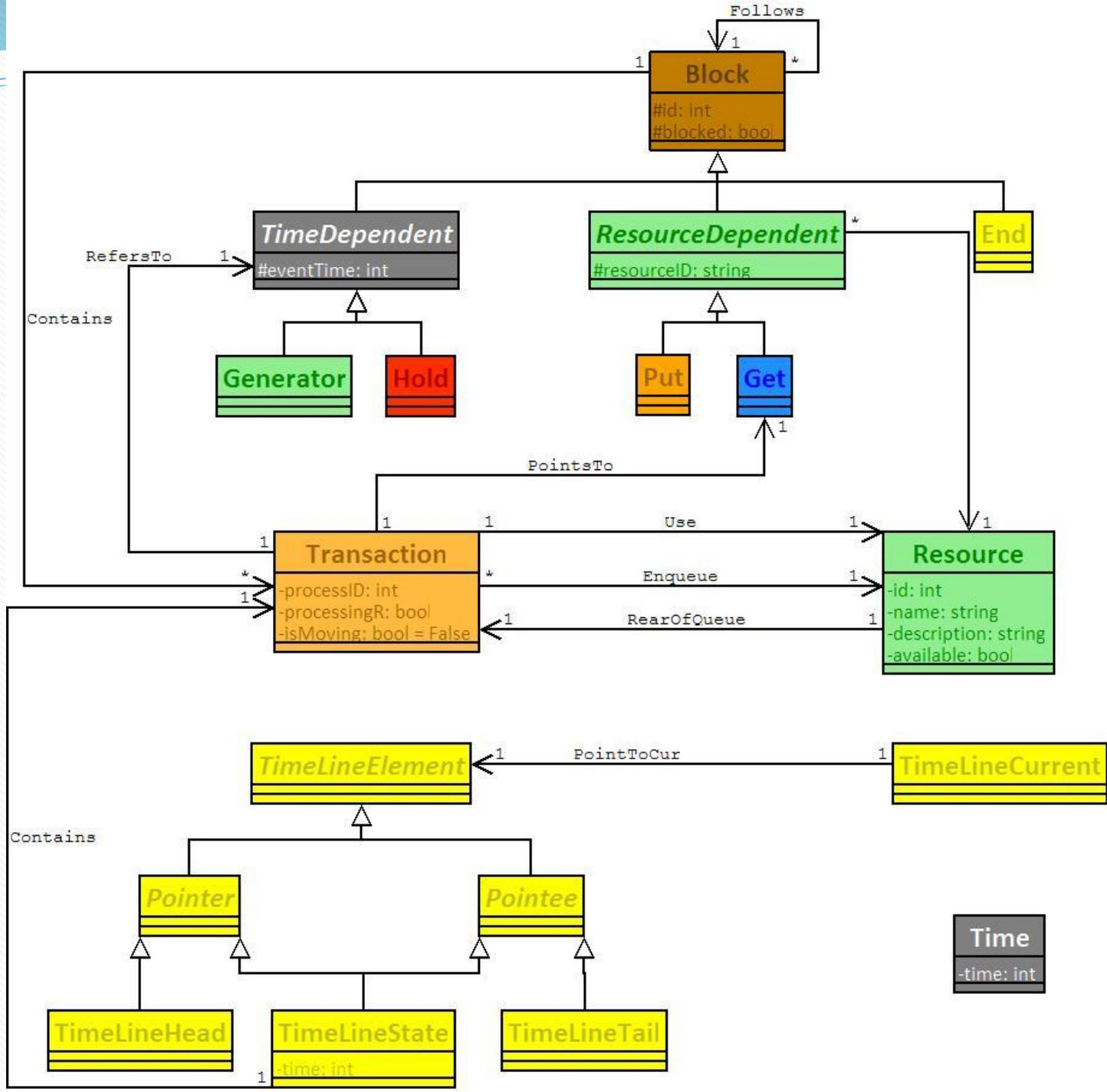
Time

- Time
- Head
- Tail
- State
- Current

UML class diagram

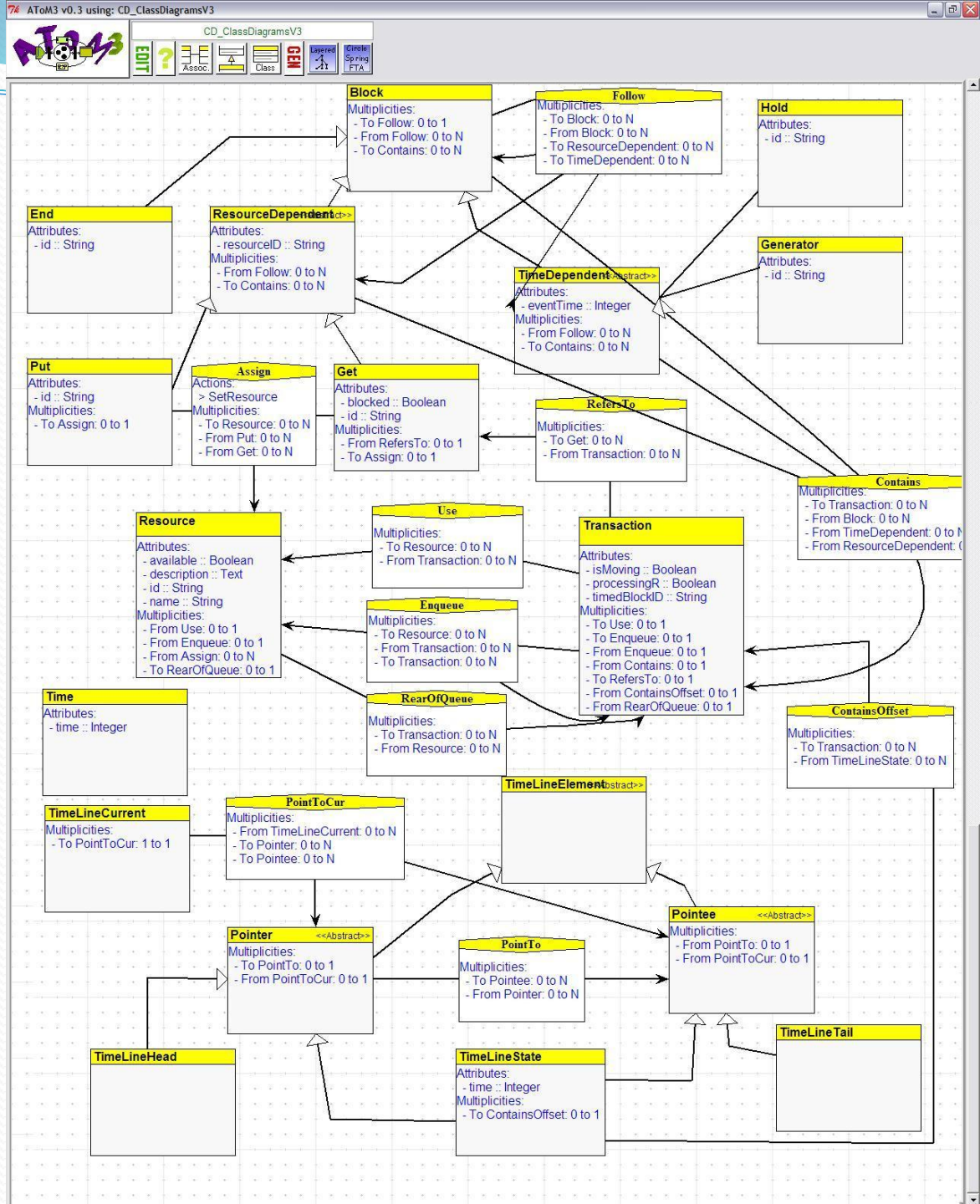


The Meta-Model

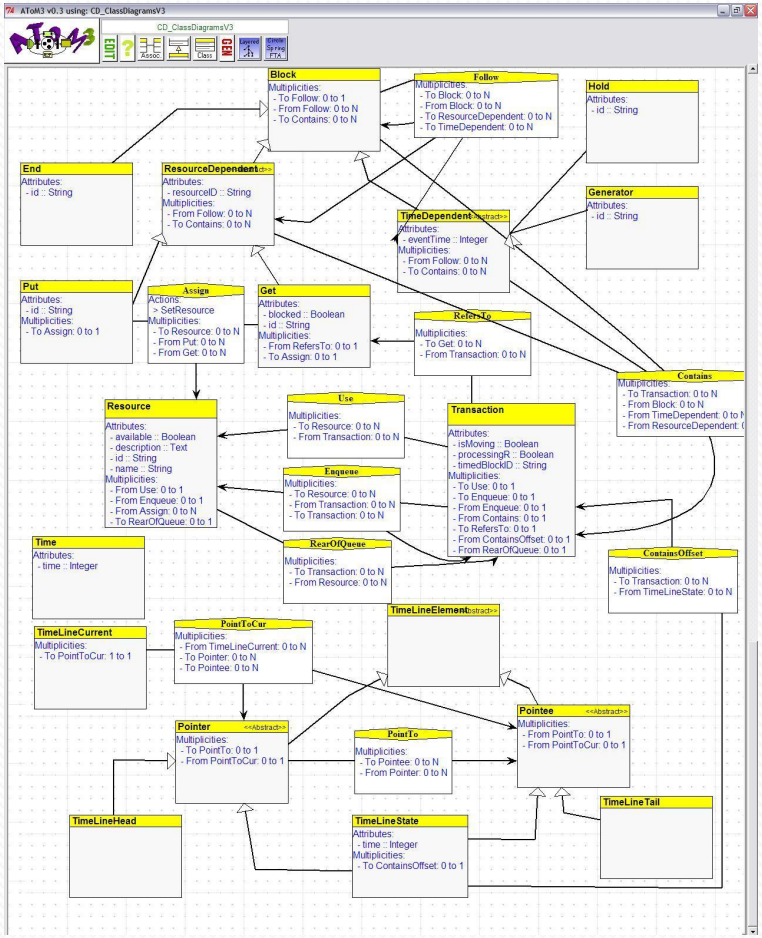


Using AToM^3

The big picture



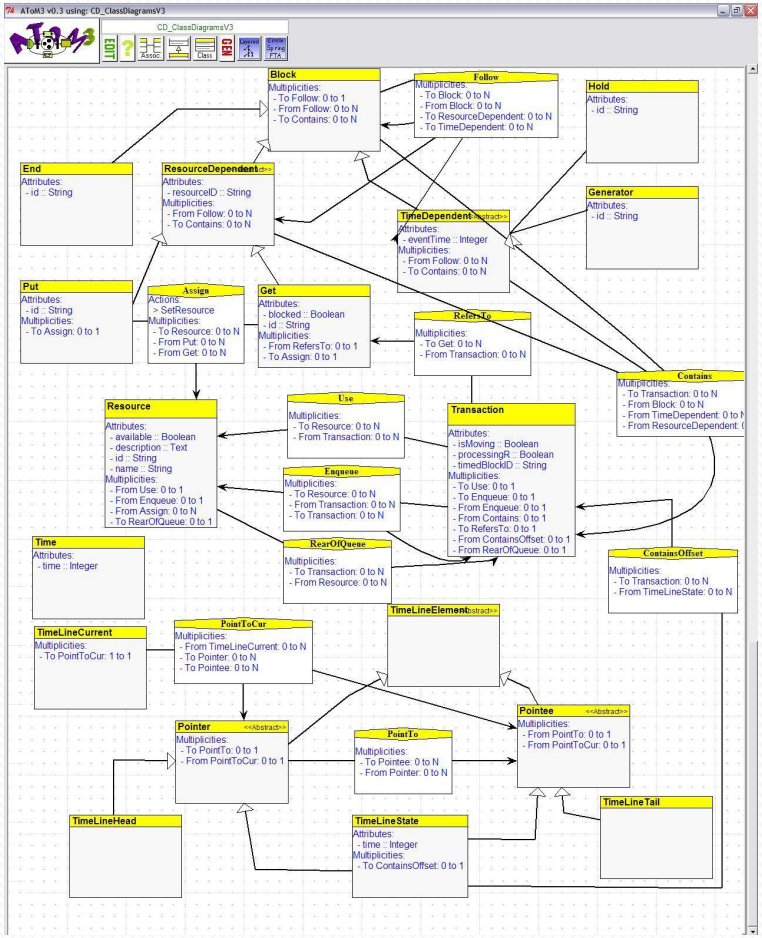
Using AToM^3



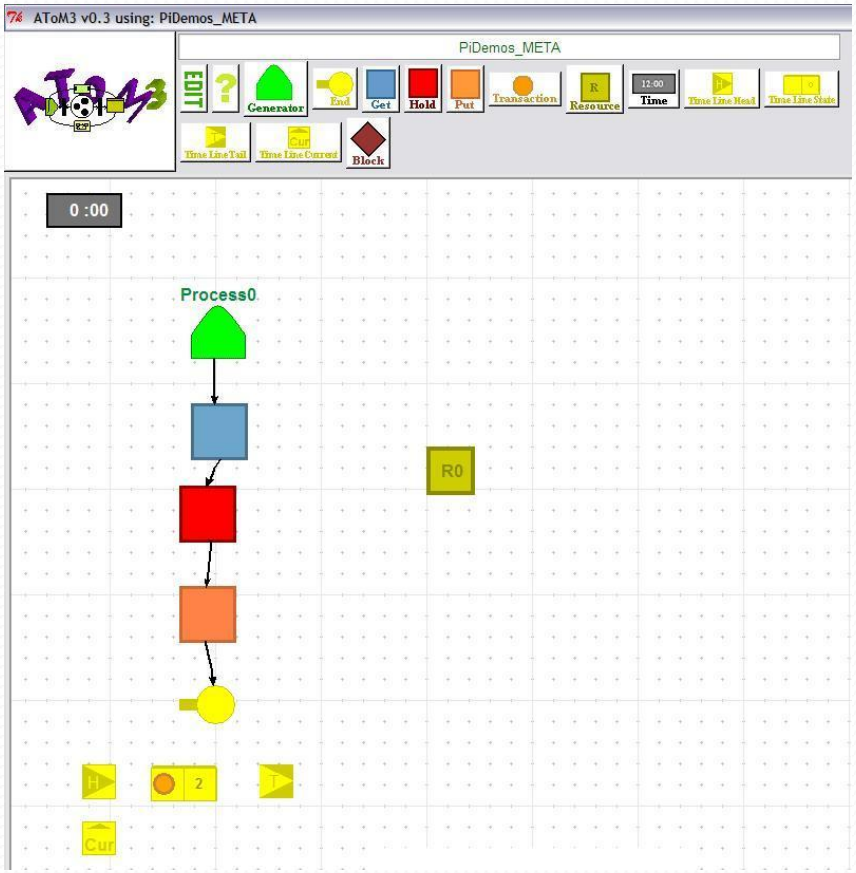
When *QOCA* is involved

```
from Qoca.atom3constraints.OffsetConstraints import OffsetConstraints
oc = OffsetConstraints(self.parent.qocaSolver)

# Constraint only makes sense if there exists 2 objects connected to this link
if(not (self.in_connections_ and self.out_connections_)): return

# Get the graphical objects (subclass of graphEntity/graphLink)
graphicalObjectLink = self.graphObject_
graphicalObjectSource = self.in_connections_[0].graphObject_
graphicalObjectTarget = self.out_connections_[0].graphObject_
objTuple = (graphicalObjectSource, graphicalObjectTarget, graphicalObjectLink)

oc.Center(objTuple)
oc.resolve() # Resolve immediately after creating entity & constraint
```

Using AToM^3



The Meta Model



A model

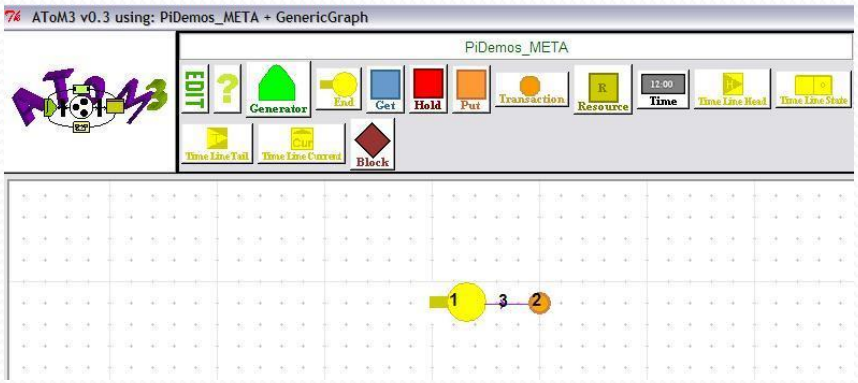
Now, let's give a meaning to the meta-model

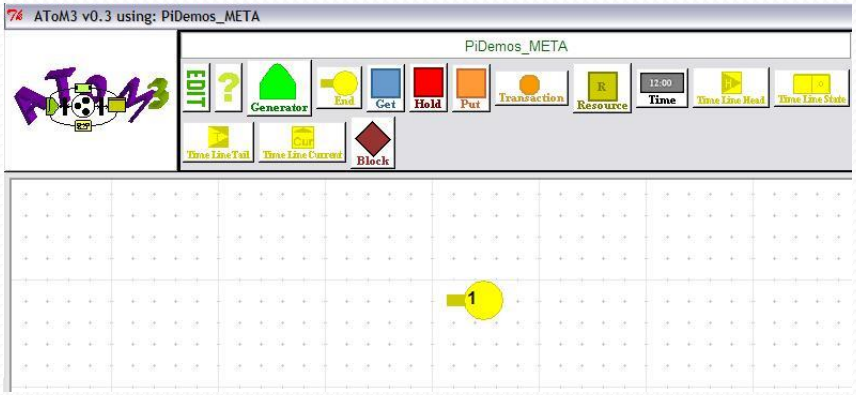
- Define a Graph Grammar
- 15 graph transformations are sufficient
- AToM^3 is a very nice and easy tool to use for graph transformations

Example: *EXIT*

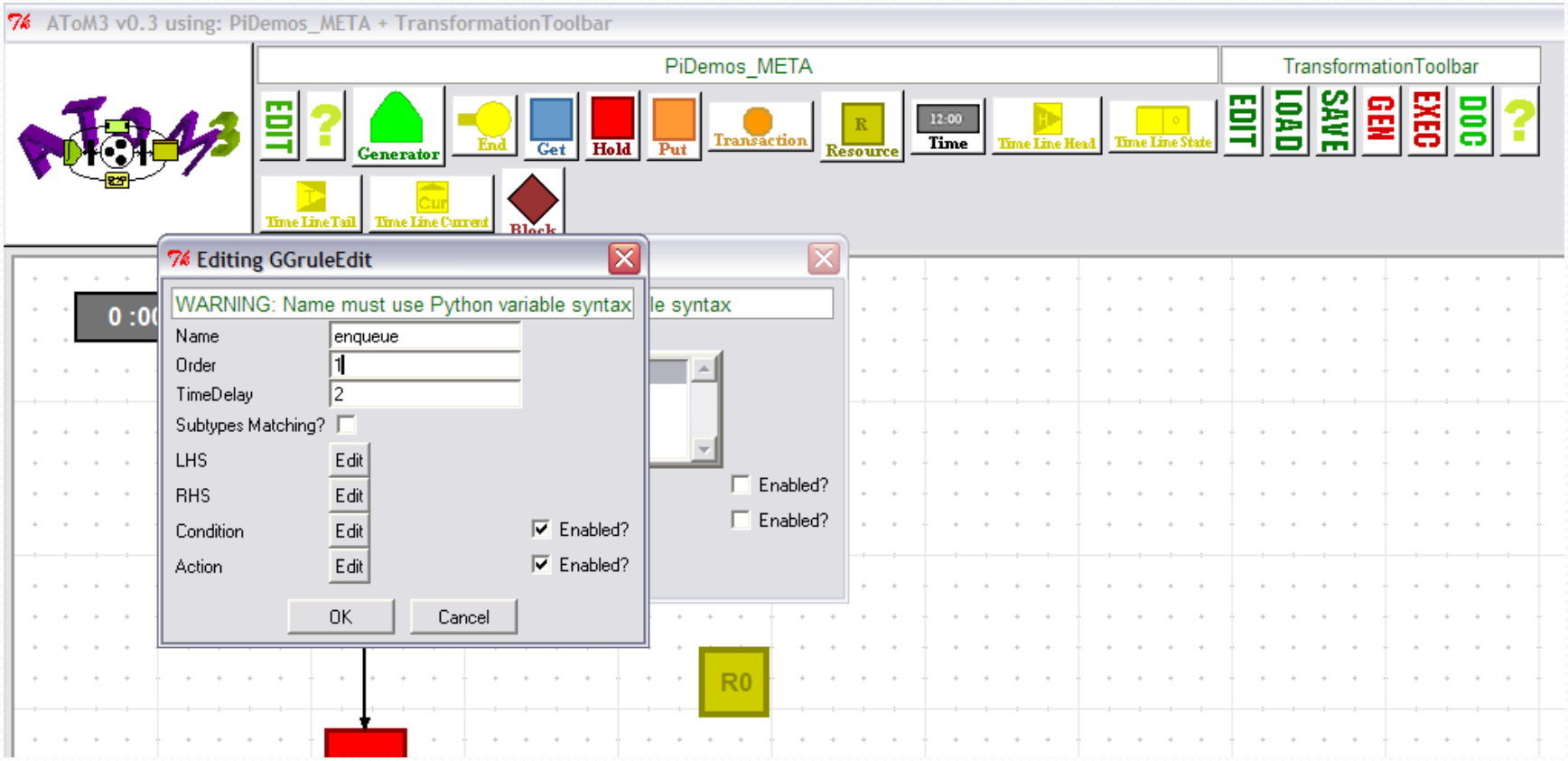
Define the LHS by means of labels on each item of a subgraph of a model instance.

On the RHS, specify what it should be replaced by





Using AToM^3


AToM3 v0.3 using: PiDemos_META + TransformationToolbar
PiDemos_META
TransformationToolbar
EDIT
Generator
End
Get
Hold
Put
Transaction
Resource
Time
Time Line Head
Time Line State
LOAD
SAVE
GEN
EXEC
DOC
Time Line Tail
Time Line Current
Block
Editing GGruleEdit
WARNING: Name must use Python variable syntax
Name
enqueue
Order
1
TimeDelay
2
Subtypes Matching?
LHS
Edit
RHS
Edit
Condition
Edit
Enabled?
Action
Edit
Enabled?
OK
Cancel
Enabled?
Enabled?
R0

The Graph Grammar

Words in action!

Further work

- Enable loops in processes, with conditions
- Non-determinism is possible
  - Closer to reality
  - Proof of termination is NP-Complete
- Let the process really do something, not just halt
  - Problem: time is not known in advance